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### **(54) DECODING METHOD THEREFOR AND PROVIDING MEDIUM**

(57)Abstract:

**PROBLEM TO BE SOLVED:** To make a scale of transcoder small and to suppress the deterioration of images caused by re-encoding.

**SOLUTION:** An encoding parameter multiplex device 103 multiplexes a present encoding parameter and an encoding parameter of plural generations included in history information which is supplied by a history encoder 104 into video data supplied by a decoder 102 and outputs it as a digital video signal of a base band to an encoding parameter separation device 105. The encoding parameter separation device 105 selects the encoding parameter to be used for encoding by an encoder 106 and outputs it as the present encoding parameter to the encoder 106 and outputs the remaining encoding parameter of plural generations to a history encoder 107. The encoder 106 encodes the video data supplied by the encoding parameter separation device 105 by the present encoding parameter and generates a bit stream; at the same time it multiplexes the data where the encoding parameter of the plural generations supplied by the history encoder 107 to the bit stream is included as history information and outputs them to a successive step transcoder.

### **CLAIMS**

[Claim(s)]

[Claim 1] A decoding device which decodes a bit stream coded based on an MPEG standard comprising:

A hysteresis information decoding means which decodes coding hysteresis information in the past coding processing inserted in user data area of a picture layer of said bit stream.

A video-data decoding means which decodes a video data from said bit stream.

[Claim 2] A decoding method of a decoding device which decodes a bit stream coded based on an MPEG standard characterized by comprising the following.

A hysteresis information decoding step which decodes coding hysteresis information in the past coding processing inserted in user data area of a picture layer of said bit stream.

A video-data decoding step which decodes a video data from said bit stream.

[Claim 3] A distribution medium providing a program which a computer characterized by comprising the following which performs processing can read.

A hysteresis information decoding step which decodes coding hysteresis information in the past coding processing inserted in user data area of a picture layer of said bit stream to a decoding device which decodes a bit stream coded based on an MPEG standard.

A video-data decoding step which decodes a video data from said bit stream.

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## DETAILED DESCRIPTION

[Detailed Description of the Invention]

[0001]

[Field of the Invention] About a decoding device, a method, and a distribution medium, especially this invention records a dynamic image signal, for example, on recording media such as a magneto-optical disc and magnetic tape, and plays this in [display on the display etc. in which stereo \*\* is possible] or a video conference system, a video telephone system, the apparatus for broadcast etc. transmit a dynamic image signal to a receiver from the transmitting side via a transmission line, and a receiver uses when receiving and displaying this, and it is related with a suitable decoding device, a method, and a distribution medium.

[0002]

[Description of the Prior Art] For example, like a video conference system and a video telephone system, in the system which transmits a dynamic image signal to a remote place in order to use a transmission line efficiently, the line correlation and inter frame correlation of a video signal are used, and compression encoding of the picture signal is carried out.

[0003] When compression encoding of the picture signal is carried out, coding is performed so that the bit stream generated may become the predetermined bit rate. However, on account of a transmission line, it may be necessary to change the bit rate of a bit stream on actual operation. In such a case, the method of coding again is common so that the information coded may once be decoded and the bit rate may become a predetermined value by the transformer coder 131.

as shown in drawing 68. In the case of the example of drawing 68 the bit stream sent by 10Mbps is decoded by the decoding device 132 and is supplied to the coding equipment 133 as a digital video signal and the bit rate is coded and outputted to the bit stream which is 5Mbps by the coding equipment 133.

[0004]

[Problem(s) to be Solved by the Invention] Thus when recoding of the video signal was carried out as shown in drawing 69 the motion detection part 134 which detects the line correlation and inter frame correlation of a video signal was needed for the coding equipment 133 and there was SUBJECT to which the scale of the coding equipment 133 becomes large in it.

[0005] It is better for the picture information of a frame to be independently with the picture information of other frames for example at a broadcasting station since edit of an image is performed by a second bit. Then so that image quality may not deteriorate even if it transmits by the low bit rate (3 thru/or 9Mbps) as shown in drawing 70 The bit stream outputted from the coding equipment 133-1 of Long GOP with many frame numbers which constitute GOP (Group of Picture) which is a set of the frame which has information in correlation The frame number which constitutes GOP with the coding equipment 133-2 of a broadcasting station is changed into little Short GOP is transmitted with a high bit rate (18 thru/or 50Mbps) and is again changed and outputted to Long GOP by the coding equipment 133-3 after the end of edit. Thus since the encoding parameter used for the degree which is coding changed when coding and decoding were repeated by picture information SUBJECT in which picture information deteriorates occurred.

[0006] While making the scale of a device small by making this invention in view of such a situation and performing recoding using the motion vector calculated in the past it makes it possible to control degradation of the picture accompanying recoding.

[0007]

[Means for Solving the Problem] written this invention is characterized by it having been alike and comprising the following at claim 1.

A hysteresis information decoding means which decodes coding hysteresis information in the past coding processing inserted in user data area of a picture layer of a bit stream.

A video-data decoding means which decodes a video data from a bit stream.

[0008] written this invention is characterized by it having been alike and comprising the following at claim 2.

A hysteresis information decoding step which decodes coding hysteresis information in the past coding processing inserted in user data area of a picture layer of a bit stream.

A video-data decoding step which decodes a video data from a bit stream.

[0009] A hysteresis information decoding step which decodes coding hysteresis information in the past coding processing in which the distribution medium according to claim 3 was inserted in user data area of a picture layer of a bit stream A program which a computer which performs processing containing a video-data decoding step which decodes a video data from a bit stream can read is provided.

[0010] In the decoding device according to claim 1 the decoding method according to claim 2 and the distribution medium according to claim 3 coding hysteresis information inserted in user data

area of a picture layer of a bit stream is decoded.

[0011]

[Embodiment of the Invention] Although an embodiment of the invention is described below it is as follows when an embodiment [ / in the parenthesis after each means ] (however an example) is added and the feature of this invention is described in order to clarify correspondence relation between each means of an invention given in a claim and following embodiments.

[0012] written this invention is characterized by it having been alike and comprising the following at claim 1.

The hysteresis information decoding means which decodes the coding hysteresis information in the past coding processing inserted in the user data area of the picture layer of a bit stream (for example history decoding device 104 of drawing 15).

The video-data decoding means which decodes a video data from a bit stream (for example decoding device 102 of drawing 15).

[0013] However of course this statement does not mean limiting to what indicated each means.

[0014] Before explaining the transformer coder which applied this invention the compression encoding of a dynamic image signal is explained. The term of a system as used herein means the overall device constituted by two or more devices a means etc.

[0015] For example like the video conference system and the video telephone system in the system which transmits a dynamic image signal to a remote place in order to use a transmission line efficiently it is made as [ carry out / compression encoding of the picture signal ] using the line correlation and inter frame correlation of a video signal.

[0016] If line correlation is used DCT (discrete cosine transform) processing can be carried out for example and a picture signal can be compressed.

[0017] If inter frame correlation is used it will become possible to compress a picture signal further and to code. For example as shown in drawing 1 when being generated by the frame images PC1 thru/or PC3 in the time t1 thru/or t3 respectively the difference of the picture signal of the frame images PC1 and PC2 is calculated PC12 is generated and the difference of the frame images PC2 and PC3 is calculated and PC23 is generated. Usually since the picture of the frame which adjoins in time does not have a so big change if both difference is calculated the differential signal will become a thing of a small value. Then a code amount is compressible if this differential signal is coded.

[0018] However the original picture cannot be restored if only the differential signal was transmitted. Then the picture of each frame is used as either of three kinds of picture types I picture P picture or B picture and it is made to carry out compression encoding of the picture signal.

[0019] That is as shown for example in drawing 2 frame F1 thru/or the picture signal of 17 frames to F17 are made into a glue PUOB picture (GOP) and it may be one unit of processing. And the picture signal of frame F1 of the head is coded as an I picture and the 2nd frame F2 processes the 3rd frame F3 as a B picture as a P picture respectively. Hereafter the frames F4 thru/or F17 of the 4th henceforth are processed by turns as B picture or a P picture.

[0020] As a picture signal of I picture the picture signal for the one frame is transmitted as it is. On the other hand as a picture signal of P picture fundamentally as shown in drawing 2 the difference from the picture signal of I picture or P picture preceded in time than it is

transmitted. Furthermore as a picture signal of B picture fundamentally as shown in drawing 3 it asks for the difference from the average value of both the frame preceded in time or the frame which carries out backward and the difference is coded.

[0021] Drawing 4 is carried out in this way and the principle of the method of coding a dynamic image signal is shown. As shown in the figures since the first frame F1 is processed as an I picture it is transmitted to a transmission line as transmission data F1X as it is (formation of a picture inner code). On the other hand since the 2nd frame F2 is processed as a B picture the difference of frame F1 preceded in time and the average value of the frame F3 which carries out backward in time is calculated and the difference is transmitted as the transmission data F2X. [0022] However if the processing as this B picture is explained still more finely they exist. [ four kinds of ] The 1st processing transmits the data of the original frame F2 as the transmission data F2X as it is and turns into the same processing as the case in I picture (intra coding) (SP1). The 2nd processing calculates the difference from the next frame F3 in time and transmits the difference (SP2) (backward prediction coding). The 3rd processing transmits difference (SP3) with frame F1 preceded in time (forward prediction coding). Furthermore the 4th processing generates difference (SP4) with the average value of the frame F3 which carries out backward to frame F1 preceded in time and transmits this as the transmission data F2X (both-directions prediction coding).

[0023] The way the transmission data of the four methods mentioned above decreases most actually is adopted.

[0024] The motion vector x1 (frame F1 and motion vector between F2) (in the case of forward prediction) between the pictures (estimated image) of the frame which serves as an object which calculates difference when transmitting difference data or both x2 (motion vector between the frames F3 and F2) (in the case of backward prediction) or x1 and x2 (in the case of both-directions prediction) are transmitted with difference data.

[0025] A differential signal (SP3) with this frame and the motion vector x3 calculate the frame F3 of P picture by using as an estimated image frame F1 preceded in time and this is transmitted as the transmission data F3X (forward prediction coding). Or the data of the original frame F3 is transmitted as the data F3X as it is again (intra coding). (SP1) As for whether it is transmitted by which method the way transmission data decreases more is chosen like the case in B picture.

[0026] Drawing 5 codes and transmits a dynamic image signal based on the principle mentioned above and the example of composition of the device which decrypts this is shown. The coding equipment 1 codes the inputted video signal and is made as [ transmit / to the recording medium 3 as a transmission line ]. And the decoding device 2 reproduces the signal recorded on the recording medium 3 and is made as [ output / this / decode and ].

[0027] In the coding equipment 1 the inputted video signal is inputted into the preprocessing circuit 11 a luminance signal and a chrominance signal (in the case of this embodiment color-difference signal) are separated there and an analog signal is changed into a digital signal with A/D converters 12 and 13 respectively. The video signal changed into the digital signal by A/D converters 12 and 13 is supplied to the frame memory 14 and is memorized. The frame memory 14 memorizes a luminance signal to the luminance-signal frame memory 15 and makes the color-difference-signal frame memory 16 memorize a color-difference signal respectively.

[0028] The format conversion circuit 17 changes into the signal of a block format the signal of the frame format memorized by the frame memory 14. That is as shown in drawing 6 let the

video signal memorized by the frame memory 14 be the data of a frame format as shown in drawing 6 (A) in which the lines of V lines of H dot were collected per line. The format conversion circuit 17 classifies this signal of one frame into M slices by making 16 lines into a unit as shown in drawing 6 (B). And each slice is divided into M macro blocks. As a macro block is shown in drawing 6 (C) it is constituted by the luminance signal corresponding to 16x16 pixels (dot) and this luminance signal is classified into block Y [1] which makes further 8x8 dots a unit thru/or Y [4]. And the Cb signal of 8x8 dots and the Cr signal of 8x8 dots are equivalent to this luminance signal of 16x16 dots.

[0029] Thus the data changed into the block format is supplied to the encoder 18 from the format conversion circuit 17 and encoding (coding) is performed here. The details are later mentioned with reference to drawing 7.

[0030] The signal encoded by the encoder 18 is outputted to a transmission line as a bit stream. For example the record circuit 19 is supplied and it is recorded on the recording medium 3 as a digital signal.

[0031] The data reproduced by the regenerative circuit 30 from the recording medium 3 is supplied to the decoder 31 of the decoding device 2 and is decoded. The details of the decoder 31 are later mentioned with reference to drawing 12.

[0032] The data decoded by the decoder 31 is inputted into the format conversion circuit 32 and is changed into a frame format from a block format. And the luminance signal of a frame format is supplied to the luminance-signal frame memory 34 of the frame memory 33 and is memorized and a color-difference signal is supplied to the color-difference-signal frame memory 35 and is memorized. The luminance signal and color-difference signal which were read from the luminance-signal frame memory 34 and the color-difference-signal frame memory 35 are changed into an analog signal by D/A converters 36 and 37 respectively and are supplied to the post-processing circuit 38. The post-processing circuit 38 compounds and outputs a luminance signal and a color-difference signal.

[0033] Next the composition of the encoder 18 is explained with reference to drawing 7. The image data coded is inputted into the motion vector detection circuit 50 by a macro block unit. The motion vector detection circuit 50 processes the image data of each frame as I picture, P picture or a B picture according to the predetermined sequence set up beforehand. Whether the picture of each frame inputted sequentially is processed as which picture of I, P or B, it is set beforehand (for example the glue PUOB picture constituted by frame F1 thru/or F17 as shown in drawing 2 and drawing 3 -- IBPBP and ... processed as B and P).

[0034] The image data of the frame (for example frame F1) processed as an I picture The image data of the frame (for example frame F2) which is transmitted and memorized by the front original image part 51a of the frame memory 51 from the motion vector detection circuit 50 and is processed as a B picture The original image part 51b transmits and memorizes and the image data of the frame (for example frame F3) processed as a P picture is transmitted and memorized by the back original image part 51c.

[0035] When the picture of the frame which should be further processed as B picture (frame F4) or a P picture (frame F5) is inputted in the following timing The image data of the first P picture (frame F3) memorized by the back original image part 51c till then it is transmitted to the front original image part 51a the image data of the following B picture (frame F4) is memorized by the original image part 51b (overwrite) and the image data of the following P picture (frame F5) is

memorized by the back original image part 51c (overwrite). Such operation is repeated successively.

[0036]The signal of each picture memorized by the frame memory 51 is read from there and frame prediction mode processing or field prediction mode processing is performed in the prediction mode switching circuit 52.

[0037]In the operation part 53 the operation of the prediction within a picture forward prediction backward prediction or both-directions prediction is performed under control of the prediction decision circuit 54 further again. It is determined corresponding to a prediction error signal (difference of the image comparison made into the object of processing and the estimated image to this) whether to perform processing [ which ] among these processings. For this reason the motion vector detection circuit 50 generates the absolute value sum (the sum of squares may be sufficient) of the prediction error signal used for this judgment.

[0038]Here the frame prediction mode and field prediction mode in the prediction mode switching circuit 52 are explained.

[0039]When frame prediction mode is set up the prediction mode switching circuit 52 outputs four luminosity block Y [1] supplied from the motion vector detection circuit 50 thru or Y [4] to the latter operation part 53 as it is. Namely it is in the state where the data of the line of an odd number field and the data of the line of an even number field were intermingled in each luminosity block as [ show / in drawing 8 ] in this case. In this frame prediction mode prediction is performed by making four luminosity blocks (macro block) into a unit and one motion vector corresponds to four luminosity blocks.

[0040]On the other hand the prediction mode switching circuit 52 as shown in drawing 9 the signal inputted from the motion vector detection circuit 50 in field prediction mode with the composition shown in drawing 8 For example luminosity block Y [1] and Y [2] are made to constitute only from a dot of the line of an odd number field among four luminosity blocks and other two luminosity block Y [3] and Y [4] are made to constitute only from a dot of the line of an even number field and are outputted to the operation part 53. In this case one motion vector corresponds to two luminosity block Y [1] and Y [2] and other one motion vector corresponds to other two luminosity block Y [3] and Y [4].

[0041]The motion vector detection circuit 50 outputs the absolute value sum of the absolute value sum of the prediction error in frame prediction mode and the prediction error in field prediction mode to the prediction mode switching circuit 52. The prediction mode switching circuit 52 compares the absolute value sum of the prediction error in frame prediction mode and field prediction mode performs processing corresponding to the prediction mode in which the value is small and outputs data to the operation part 53.

[0042]However such processing is performed actually in the motion vector detection circuit 50. That is the motion vector detection circuit 50 outputs the signal of the composition corresponding to the determined mode to the prediction mode switching circuit 52 and the prediction mode switching circuit 52 outputs the signal to the latter operation part 53 as it is.

[0043]In the case of frame prediction mode as shown in drawing 8a a color-difference signal is in the state where the data of the line of an odd number field and the data of the line of an even number field are intermingled and is supplied to the operation part 53. In the case of field prediction mode as shown in drawing 9 each color difference block Cb and the upper half (four lines) of CrI is considered as the color-difference signal of the odd number field corresponding

to luminosity block Y [1] and Y [2] and a lower half (four lines) is made into the color-difference signal of the even number field corresponding to luminosity block Y [3] and Y [4].

[0044] As the motion vector detection circuit 50 is shown below in the prediction decision circuit 54, it generates the absolute value sum of the prediction error for determining whether to perform prediction [which / of the prediction within a picture: forward prediction, backward prediction, or both-directions prediction].

[0045] That is, the difference of total  $\sum |A_{ij}|$  of absolute value  $|\sum A_{ij}|$  of total  $\sum A_{ij}$  of the signal  $A_{ij}$  of the macro block of an image comparison and absolute value  $|A_{ij}|$  of the signal  $A_{ij}$  of a macro block is searched for as an absolute value sum of the prediction error of the prediction within a picture. It asks for total  $\sum |A_{ij} - B_{ij}|$  of absolute value  $|A_{ij} - B_{ij}|$  of difference  $A_{ij} - B_{ij}$  of the signal  $A_{ij}$  of the macro block of an image comparison and the signal  $B_{ij}$  of the macro block of an estimated image as an absolute value sum of the prediction error of forward prediction. It asks for the absolute value sum of the prediction error of backward prediction and both-directions prediction as well as (changing the estimated image into a different estimated image from the case in forward prediction) the case in forward prediction.

[0046] These absolute value sums are supplied to the prediction decision circuit 54. The prediction decision circuit 54 chooses the smallest thing of the absolute value sums of the prediction error of forward prediction, backward prediction, and both-directions prediction as an absolute value sum of the prediction error of the Intra prediction. The absolute value sum of the prediction error of this Intra prediction is compared with the absolute value sum of the prediction error of the prediction within a picture; the smaller one of it is chosen, and the mode corresponding to this selected absolute value sum is chosen as prediction mode. That is, if the absolute value sum of the prediction error of the prediction within a picture is smaller, the prediction mode within a picture will be set up. If the absolute value sum of the prediction error of the Intra prediction is smaller, the mode whose absolute value sum to which it corresponds of forward prediction, backward prediction, or the both-directions prediction modes was the smallest will be set up.

[0047] Thus, the motion vector detection circuit 50 is the composition corresponding to the mode chosen by the prediction mode switching circuit 52 among a frame or field prediction mode in the signal of the macro block of an image comparison. While supplying the operation part 53 via the prediction mode switching circuit 52, the motion vector between the estimated image corresponding to the prediction mode in which the prediction decision circuit 54 of the four prediction modes was selected and an image comparison is detected, and it outputs to the variable-length-coding circuit 58 and the motion compensation circuit 64. As mentioned above, that from which the corresponding absolute value sum of a prediction error serves as the minimum as this motion vector is chosen.

[0048] When the motion vector detection circuit 50 has read the image data of I picture from the front original image part 51a in the prediction decision circuit 54, as prediction mode, frame or field (picture) inner prediction mode (mode in which a motion compensation is not performed) is set up, and the switch 53d of the operation part 53 is changed to the point-of-contact a side. Thereby, the image data of I picture is inputted into the DCT mode switching circuit 55.

[0049] As shown in [drawing 10](#) or [drawing 11](#), the DCT mode switching circuit 55: The data of four luminosity blocks is changed into the state (frame DCT mode) where the line of an odd number



field and the line of an even number field are intermingled or the separated state (field DCT mode) and the state of \*\*\*\*\* and is outputted to DCT circuit 56.

[0050] That is the DCT mode switching circuit 55 compares the encoding efficiency at the time of being intermingled and carrying out DCT processing of the data of an odd number field and an even number field with the encoding efficiency at the time of carrying out DCT processing in the state where it dissociates and chooses the mode with good encoding efficiency.

[0051] For example, the inputted signal is considered as the composition in which the line of an odd number field and an even number field is intermingled as shown in drawing 10 the difference of the signal of the line of an odd number field and the signal of the line of an even number field which adjoins up and down is calculated and it asks for the sum (or sum of squares) of the absolute value further.

[0052] The inputted signal is considered as the composition which the line of an odd number field and an even number field separated as shown in drawing 11 the difference of the signal of the lines of the odd number field which adjoins up and down and the difference of the signal of the lines of an even number field are calculated and it asks for the sum (or sum of squares) of each absolute value.

[0053] Both (absolute value sum) are compared and the DCT mode corresponding to a small value is set up. That is if former one is small frame DCT mode will be set up and if latter one is small field DCT mode will be set up.

[0054] And while outputting the data of the composition corresponding to the selected DCT mode to DCT circuit 56 the DCT flag which shows the selected DCT mode is outputted to the variable-length-coding circuit 58 and the motion compensation circuit 64.

[0055] The prediction mode (drawing 8 and drawing 9) in the prediction mode switching circuit 52 is compared with the DCT mode (drawing 10 and drawing 11) in this DCT mode switching circuit 55 and the data structure [ in / about a luminosity block / each mode of both ] is substantially the same so that clearly.

[0056] Also in [ when frame prediction mode (mode in which an odd line and an even line are intermingled) is chosen in the prediction mode switching circuit 52 ] the DCT mode switching circuit 55 in [ a possibility that frame DCT mode (mode in which an odd line and an even line are intermingled) will be chosen is high and ] the prediction mode switching circuit 52 When field prediction mode (mode in which the data of an odd number field and an even number field was separated) is chosen in the DCT mode switching circuit 55 a possibility that field DCT mode (mode in which the data of an odd number field and an even number field was separated) will be chosen is high.

[0057] However, the mode not necessarily always is not necessarily chosen in this way the mode is determined that the absolute value sum of a prediction error will become small in the prediction mode switching circuit 52 and the mode is determined that encoding efficiency will become good in the DCT mode switching circuit 55.

[0058] It is inputted into DCT circuit 56 DCT processing is carried out and the image data of 1 picture outputted from the DCT mode switching circuit 55 is changed into a DCT coefficient. This DCT coefficient is inputted into the variable-length-coding circuit 58 after being inputted into the quantization circuit 57 and quantized with the quantizing scale corresponding to the data accumulation amount (buffer accumulated dose) of the transmission buffer 59.

[0059] Corresponding to the quantizing scale (scale) supplied from the quantization circuit 57 the

image data (in the case of now data of I picture) supplied from the quantization circuit 57 is changed into variable length codessuch as Huffman codingfor exampleand the variable-length-coding circuit 58 outputs it to the transmission buffer 59.

[0060]In the variable-length-coding circuit 58from the quantization circuit 57 again A quantizing scale (scale)the prediction decision circuit 54 – prediction mode (the prediction within a pictureforward predictionand backward prediction.) Any of both-directions prediction were set up from the mode and the motion vector detection circuit 50 which are shown Or a motion vectorFrom the prediction mode switching circuit 52a prediction flag (flag which shows any should be set up between frame prediction mode or field prediction mode)And the DCT flag (flag which shows any should be set up between frame DCT mode or field DCT mode) which the DCT mode switching circuit 55 outputs is inputtedand variable length coding also of these is carried out.

[0061]The transmission buffer 59 stores the inputted data temporarilyand outputs the data corresponding to an accumulated dose to the quantization circuit 57. The transmission buffer 59 will reduce the data volume of quantization data by enlarging the quantizing scale of the quantization circuit 57 with a quantized control signalif the data residue increases to permission upper limit. Contrary to thisif a data residue decreases to a permission lower limitthe transmission buffer 59 will increase the data volume of quantization data by making the quantizing scale of the quantization circuit 57 small with a quantized control signal. Thusoverflow or underflow of the transmission buffer 59 is prevented.

[0062]And the data stored in the transmission buffer 59 is read to predetermined timingand is outputted to a transmission linefor exampleis recorded on the recording medium 3 via the record circuit 19.

[0063]On the other handthe data of I picture outputted from the quantization circuit 57 is inputted into the inverse quantizing circuit 60and inverse quantization is carried out corresponding to the quantizing scale supplied from the quantization circuit 57. The output of the inverse quantizing circuit 60 is inputted into the IDCT (reverse discrete cosine transform) circuit 61and after reverse discrete cosine transform processing is carried outvia the computing unit 62forward prediction picture part 63a supply of the frame memory 63 is carried outand it is memorized.

[0064]The motion vector detection circuit 50 the image data of each frame inputted sequentiallyFor exampleIBPPB ... When processing as a picturerespectivelyAfter processing the image data of the frame inputted first as an I picturebefore processing the picture of the frame inputted into the next as a B picturethe image data of the frame further inputted into the next is processed as a P picture. It is because it cannot decode unless P picture as a backward prediction image is prepared previouslyin order to accompany B picture by backward prediction.

[0065]Thenthe motion vector detection circuit 50 is processing of I picturenext starts processing of the image data of P picture memorized by the back original image part 51c. And the absolute value sum of the inter-frame difference (prediction error) in a macro block unit is supplied to the prediction mode switching circuit 52 and the prediction decision circuit 54 from the motion vector detection circuit 50 like the case where it mentions above. The prediction mode switching circuit 52 and the prediction decision circuit 54 set up the prediction mode of a frame / field prediction mode or the prediction within a pictureforward predictionbackward predictionor both-directions prediction corresponding to the absolute value sum of the

prediction error of the macro block of this P picture.

[0066]When the prediction mode within a picture is set up the operation part 53 is changed to the point-of-contact a side as the switch 53d was mentioned above. Therefore this data is transmitted to a transmission line like the data of I picture via the DCT mode switching circuit 55, DCT circuit 56, the quantization circuit 57, the variable-length-coding circuit 58 and the transmission buffer 59. Via the inverse quantizing circuit 60, the IDCT circuit 61 and the computing unit 62, this data is supplied to the backward prediction picture part 63b of the frame memory 63 and is memorized.

[0067]When forward prediction mode is set up while the switch 53d is changed to the point of contact b, the picture (in case of now picture of I picture) data memorized by the forward prediction picture part 63a of the frame memory 63 is read and a motion compensation is carried out by the motion compensation circuit 64 corresponding to the motion vector which the motion vector detection circuit 50 outputs. Namely, when it is ordered the motion compensation circuit 64 in setting out in forward prediction mode from the prediction decision circuit 54, only the part corresponding to the position lost-motion vector corresponding to the position of the macro block to which the motion vector detection circuit 50 is outputting the reading address of the forward prediction picture part 63a now is shifted, data is read and prediction image data is generated.

[0068]The prediction image data outputted from the motion compensation circuit 64 is supplied to the computing unit 53a. The computing unit 53a subtracts the prediction image data corresponding to this macro block supplied from the motion compensation circuit 65 from the data of the macro block of the image comparison supplied from the prediction mode switching circuit 52 and outputs that difference (prediction error). This difference data is transmitted to a transmission line via the DCT mode switching circuit 55, DCT circuit 56, the quantization circuit 57, the variable-length-coding circuit 58 and the transmission buffer 59. This difference data is locally decoded by the inverse quantizing circuit 60 and the IDCT circuit 61 and is inputted into the computing unit 62.

[0069]The same data as the prediction image data currently supplied to the computing unit 53a is supplied to this computing unit 62 again. The computing unit 62 adds the prediction image data which the motion compensation circuit 64 outputs to the difference data which the IDCT circuit 61 outputs. Thereby, the image data of the original P (it decoded) picture is obtained. The image data of this P picture is supplied to the backward prediction picture part 63b of the frame memory 63 and is memorized.

[0070]In this way, the motion vector detection circuit 50 performs processing of B picture next after the data of I picture and P picture is memorized by the forward prediction picture part 63a and the backward prediction picture part 63b respectively. The prediction mode switching circuit 52 and the prediction decision circuit 54 corresponding to the size of the absolute value sum of the inter-frame difference in a macro block unit, a frame/field mode is set up and prediction mode is set to either the prediction mode within a picture, forward prediction mode, backward prediction mode or both-directions prediction mode.

[0071]As mentioned above, the switch 53d is changed to the point of contact a or b at the time of the prediction mode within a picture or forward prediction mode. At this time, the same processing as the case in P picture is performed and data is transmitted.

[0072]On the other hand, when backward prediction mode or both-directions prediction mode is

set up the switch 53d is changed to the point of contact c or respectively.

[0073] It is read by the picture (in case of now picture of P picture) data memorized by the backward prediction picture part 63b at the time of the backward prediction mode in which the switch 53d is changed to the point of contact c and by the motion compensation circuit 64. A motion compensation is carried out corresponding to the motion vector which the motion vector detection circuit 50 outputs. Namely when it is ordered the motion compensation circuit 64 in setting out in backward prediction mode from the prediction decision circuit 54 Only the part corresponding to the position lost-motion vector corresponding to the position of the macro block to which the motion vector detection circuit 50 is outputting the reading address of the backward prediction picture part 63b now is shifted data is read and prediction image data is generated.

[0074] The prediction image data outputted from the motion compensation circuit 64 is supplied to the computing unit 53b. The computing unit 53b subtracts the prediction image data supplied from the motion compensation circuit 64 from the data of the macro block of the image comparison supplied from the prediction mode switching circuit 52 and outputs the difference. This difference data is transmitted to a transmission line via the DCT mode switching circuit 55 DCT circuit 56 the quantization circuit 57 the variable-length-coding circuit 58 and the transmission buffer 59.

[0075] The picture (in case of now picture of I picture) data memorized by the forward prediction picture part 63a at the time of the both-directions prediction mode in which the switch 53d is changed to the point of contact d The picture (in case of now picture of P picture) data memorized by the backward prediction picture part 63b is read and a motion compensation is carried out by the motion compensation circuit 64 corresponding to the motion vector which the motion vector detection circuit 50 outputs.

[0076] Namely when it is ordered the motion compensation circuit 64 in setting out in both-directions prediction mode from the prediction decision circuit 54 The reading address of the forward prediction picture part 63a and the backward prediction picture part 63b The motion vector detection circuit 50 shifts only the part corresponding to the position lost-motion vector (the motion vector in this case is set to two the object for forward prediction pictures and the object for backward prediction pictures) corresponding to the position of the macro block outputted now reads data and generates prediction image data.

[0077] The prediction image data outputted from the motion compensation circuit 64 is supplied to the computing unit 53c. The computing unit 53c subtracts the average value of the prediction image data supplied from the motion compensation circuit 64 from the data of the macro block of the image comparison supplied from the motion vector detection circuit 50 and outputs the difference. This difference data is transmitted to a transmission line via the DCT mode switching circuit 55 DCT circuit 56 the quantization circuit 57 the variable-length-coding circuit 58 and the transmission buffer 59.

[0078] Since the picture of B picture is not used as the estimated image of other pictures it is not memorized by the frame memory 63.

[0079] In the frame memory 63 bank switching is performed if needed and to a predetermined image comparison the forward prediction picture part 63a and the backward prediction picture part 63b can change what is memorized on one side or another side as a forward prediction picture or a backward prediction picture and can output it.

[0080]In the explanation mentioned above although explained focusing on the luminosity block about a color difference block similarly it is processed as a unit and the macro block shown in drawing 8 thru/or drawing 11 is transmitted. What set to one half the motion vector of the luminosity block with which the motion vector in the case of processing a color difference block corresponds to the perpendicular direction and the horizontal direction respectively is used.

[0081]Drawing 12 is a block diagram showing the composition of the decoder 31 of drawing 5. After being received in the receiving circuit which is not illustrated or being reproduced with playback equipment and storing temporarily the coded image data which was transmitted via the transmission line (recording medium 3) at the receive buffer 81 it is supplied to the variable length decoding circuit 82 of the decoder circuit 90. The variable length decoding circuit 82 carries out variable-length decryption of the data supplied from the receive buffer 81 while outputting a motion vector prediction mode a prediction flag and a DCT flag to the motion compensation circuit 87 and outputting a quantizing scale to the inverse quantizing circuit 83 the decoded image data is outputted to the inverse quantizing circuit 83.

[0082]The inverse quantizing circuit 83 carries out inverse quantization of the image data supplied from the variable length decoding circuit 82 according to the quantizing scale similarly supplied from the variable length decoding circuit 82 and outputs it to the IDCT circuit 84. Reverse discrete cosine transform processing is performed by the IDCT circuit 84 and the data (DCT coefficient) outputted from the inverse quantizing circuit 83 is supplied to the computing unit 85.

[0083]When the image data supplied to the computing unit 85 from the IDCT circuit 84 is data of I picture The data is outputted from the computing unit 85 for prediction-image-data generation of the image data (data of P or B picture) behind inputted into the computing unit 85 is supplied to the forward prediction picture part 86a of the frame memory 86 and is memorized. This data is outputted to the format conversion circuit 32 (drawing 5).

[0084]The image data supplied from the IDCT circuit 84 is data of P picture which uses the image data in front of one of them as prediction image data When it is data in forward prediction mode the image data (data of I picture) before [ one ] the forward prediction picture part 86a of the frame memory 86 memorizes is read and the motion compensation corresponding to the motion vector outputted from the variable length decoding circuit 82 in the motion compensation circuit 87 is given. And in the computing unit 85 it is added with the image data (data of difference) supplied from the IDCT circuit 84 and is outputted. For prediction-image-data generation of the image data (data of B picture or P picture) behind inputted into the computing unit 85 this added data i.e. the decoded data of P picture is supplied to the backward prediction image part 86b of the frame memory 86 and it is memorized.

[0085]Even if it is data of P picture as for the data in the prediction mode within a picture like the data of I picture processing is not performed in the computing unit 85 but the backward prediction picture part 86b memorizes as it is.

[0086]Since this P picture is a picture which should be displayed on the next of the following B picture it is not outputted to the format conversion circuit 32 yet at this time (as mentioned above P picture inputted after B picture is processed ahead of B picture and is transmitted).

[0087]When the image data supplied from the IDCT circuit 84 is data of B picture it corresponds to the prediction mode supplied from the variable length decoding circuit 82 The image data of I picture memorized by the forward prediction picture part 86a of the frame memory 86 (in the

case of forward prediction mode)The image data of P picture memorized by the backward prediction picture part 86b (in the case of backward prediction mode)Or the image data (in the case of both-directions prediction mode) of the both is readthe motion compensation corresponding to the motion vector outputted from the variable length decoding circuit 82 is given in the motion compensation circuit 87and an estimated image is generated. Howeveran estimated image is not generated when you do not need a motion compensation (in the case of the prediction mode within a picture).

[0088]Thus the data in which the motion compensation was given is added with the output of the IDCT circuit 84 in the computing unit 85 in the motion compensation circuit 87. This added output is outputted to the format conversion circuit 32.

[0089]However this added output is data of B picture and since it is not used for estimated image generation of other pictures it is not memorized by the frame memory 86.

[0090]After the picture of B picture is outputted the image data of P picture memorized by the backward prediction picture part 86b is read and the computing unit 85 is supplied via the motion compensation circuit 87. However a motion compensation is not performed at this time.

[0091]Although the circuit corresponding to the prediction mode switching circuit 52 and the DCT mode switching circuit 55 in the encoder 18 of drawing 5 is not illustrated by this decoder 31The processing corresponding to these circuits i.e. the processing which returns the composition from which the signal of the line of an odd number field and an even number field was separated to the original composition if needed is performed by the motion compensation circuit 87.

[0092]In the explanation mentioned above although processing of the luminance signal was explained processing of a color-difference signal is performed similarly. However as for the motion vector in this case a perpendicular direction and the thing horizontally set to one half are used in the motion vector for luminance signals.

[0093]Drawing 13 shows the quality of the coded picture. The quality (SNR: Signal to Noise Ratio) of a picture is controlled corresponding to a picture type I picture and P picture are made quality and B picture is made into the quality which is inferior compared with I and P picture and is transmitted. This is a technique using human being's vision characteristics and the way which vibrated quality is because the image quality on vision becomes good rather than equalizing all the imaging quality. Control of the image quality corresponding to this picture type is performed by the quantization circuit 57 of drawing 7.

[0094]Drawing 14 shows the composition of the transformer coder 101 which applied this invention and drawing 15 shows the still more detailed composition. The decoding device 102 the coded picture signal which is included in the bit stream of the predetermined bit rate (in the case of this example 10Mbps) (it has multiplexed) the present encoding parameter (a frame / field DCT flag.) of the bit stream contained in a bit stream (it has multiplexed) While decoding using a frame / field prediction flag prediction mode a picture type a motion vector macro block information and a quantizing scale and outputting to the encoding parameter multiplexer 103 It is made as [ output / to the encoding parameter multiplexer 103 / the present encoding parameter ].

[0095]The user datum contained in a bit stream is decoded it dissociates again and the decoding device 102 is outputted to the history decoding device 104. Although those details are mentioned later the generation hysteresis information which comprises an encoding parameter

for three latest generations is included in this user datum. The present encoding parameter for example On the other hand group\_of\_pictures\_header(1) extension\_and\_user\_data (1) picture\_header() It is contained in picture\_coding\_extension() extensions\_data (2) picture\_data() or sequence\_extension() (drawing 38 mentioned later). The history decoding device 104 decodes the inputted user datum and outputs the generation hysteresis information containing the encoding parameter for three generations to the encoding parameter multiplexer 103.

[0096] The decoding device 102 is changed into the decoder 111 which shows drawing 16 the decoder 31 (drawing 12) of the decoding device 2 of drawing 5. The variable length decoding circuit 112 of the decoder 111 extracts an user datum including generation hysteresis information and is made as [ output / to the history decoding device 104 ] while extracting the present encoding parameter from a bit stream and supplying a predetermined circuit. Since the composition of others of the decoder 111 is the same as that of the decoder 31 the explanation is omitted.

[0097] Free space of image data where the encoding parameter multiplexer 103 was decoded (the details) The encoding parameter for four generations is written in for explaining with reference to drawing 18 (multiplexing) and it outputs to the encoding parameter (dedicated bus for encoding parameter transmission etc. are not provided) decollator 105 by which rough union was carried out as a digital video signal of baseband. The encoding parameter decollator 105 is made as [ supply / separate image data and the encoding parameter used for coding with the coding equipment 106 from the digital video signal of baseband and / the coding equipment 106 ].

[0098] The encoding parameter decollator 105 extracts again the encoding parameter for three generations except the encoding parameter used with the coding equipment 106 from the inputted digital video signal of baseband and outputs it to the history coding equipment 107. The history coding equipment 107 writes the encoding parameter for three inputted generations in an user datum and outputs the user datum to the coding equipment 106.

[0099] The format of the image data in which code parameters are written is explained with reference to drawing 17 and drawing 18. One macro block comprises 16x16 pixels as shown in drawing 17. This 16x16-pixel data comprises luminance-signal Y[0] [x] thru/or Y[4] [x] 8x8-pixel color-difference-signal Cr [0] [x] Cr[1] [x] and Cb[0] [x] and Cb[1] [x] (x= 2 thru/or 9) 8x8-pixel. For example luminance-signal Y [0] and [9] show the luminance signal of the 8x8-pixel pixel (8 pixels) of the 1st line. Since the amount of information of the luminance signal per pixel is 8 bits the amount of information of luminance-signal Y [0] and [9] will be 8(pixel)x8(bit)=64 bit. The same may be said of a color-difference signal.

[0100] On the other hand since the field for ten lines (D0 thru/or D9) is provided as shown in drawing 18 the format of image data becomes unnecessary [ the field for two lines (D0D1) ]. Since information (64 bits x 16= 1024 bits) is recordable on this free space encoding parameters other than original image data are written in the field for these two lines. Since the encoding parameter corresponding to one macro block has the amount of information of 256 bits it can record the encoding parameter used for the past four coding on this field.

[0101] The field for ten lines (D0 thru/or D9) is established in the image data (digital video signal) transmitted to the encoding parameter decollator 105 from the encoding parameter multiplexer 103 as a field which indicates the luminance signal Y the color-difference signal

Grand Cb. However the field where the luminance signal Y etc. are actually written in is a field for eight lines of D2 thru/or D9 and the field of D0 and D1 is not used. Then this 2-bit field is used as a field for writing of an encoding parameter. By this an encoding parameter will be written in 2 bits of low ranks of the pixel of the 16x16-pixel position of drawing 17.

[0102] While the coding equipment 106 codes image data using the present encoding parameter supplied as an encoding parameter for the coding to be performed from now on, the user datum supplied from the history coding equipment 107 is multiplexed to a bit stream. It is made as [ output / to SDTI (Serial Data Transfer Interface) 108-i (i= 12...N) (drawing 30 mentioned later) / by the predetermined bit rate (in the case of this example 5Mbps) ].

[0103] The coding equipment 106 is changed into the encoder 121 which shows drawing 19 the encoder 18 (drawing 7) of the coding equipment 1 of drawing 5. The encoder 121 deletes the motion vector detection circuit 50 which generates an encoding parameter, the frame memory 51, the prediction mode switching circuit 52, the prediction decision circuit 54, and the DCT mode switching circuit 55 from the encoder 18. It is made to carry out variable length coding of the user datum which the history coding equipment 107 outputs in the variable-length-coding circuit 58. Since the composition of others of the encoder 121 is the same as that of the encoder 18, the explanation is omitted.

[0104] Next, the history decoding device 104 and the history coding equipment 107 in drawing 15 are explained further. As shown in the figure, the history decoding device 104 consists of the converter 202 which changes the output of the user-datum decoder 201 which decodes the user datum supplied from the decoding device 102, and the user-datum decoder 201, and the converter 202 are consisted of by the history decoder 203 which reproduces hysteresis information.

[0105] The history coding equipment 107 consists of the converter 212 and the converter 212 which change the output of the history formatter 211 which formats the encoding parameter for three generations supplied from the encoding parameter decollator 105, and the history formatter 211. It is constituted by the user-datum formatter 213 formatted into the format of an user datum.

[0106] The user-datum decoder 201 decodes the user datum supplied from the decoding device 102 and outputs it to the converter 202. Although mentioned later for details, the user datum (user\_data()) consisted of user\_data\_start\_code and user\_data\_end and has forbidden generating "0" which continues into user\_data in an MPEG standard. [ 23-bit ] This is for not carrying out erroneous detection of start\_code. Since such continuous "0" may exist in hysteresis information, it is necessary to process this and to change into converted\_history\_stream() (drawing 38 mentioned later). [ of 23 bits or more ] The converter 212 of the history coding equipment 107 performs this conversion. The converter 202 of the history decoding device 104 performs a conversion process contrary to this converter 212.

[0107] The history decoder 203 generates hysteresis information from the output of the converter 202 and outputs it to the encoding parameter multiplexer 103.

[0108] On the other hand, in the history coding equipment 107, the history formatter 211 changes into the format of hysteresis information the encoding parameter for three generations supplied from the encoding parameter decollator 105. There are a fixed-length thing (drawing 40 thru/or drawing 46 mentioned later) and a variable-length thing (drawing 47 mentioned later) in this format. These details are mentioned later.



[0109]The hysteresis information by which formatting was carried out is changed into converted\_history\_stream() in the converter 212 by the history formatter 211. This is for not carrying out erroneous detection of start\_code of user\_data()as mentioned above. That isalthough continuous "0" exists in hysteresis informationsince "0" which continues into user\_data cannot be arrangeddata is changed by the converter 212 so that this prohibition item cannot be touched. [ of 23 bits or more ] [ of 23 bits or more ]

[0110]The user-datum formatter 213 to converted\_history\_stream() supplied from the converter 212. Based on drawing 38 mentioned laterData\_ID is addedfurtheruser\_data\_stream\_code is addeduser\_data which can be inserted into video stream is generatedand it outputs to the coding equipment 106.

[0111]Drawing 20 expresses the example of composition of the history formatter 211. In the symbolic-language converter 301 and code length converter 305. An encoding parameter (encoding parameter transmitted as hysteresis information this time) (item data)The information (for examplename of syntax) (for examplename of sequence\_header mentioned later) (item NO.) which specifies the stream which arranges this encoding parameter is supplied from the encoding parameter decollator 105. The inputted encoding parameter is changed into the symbolic language corresponding to the syntax to which it was directedand the symbolic-language converter 301 outputs it to the barrel shifter 302. The barrel shifter 302 shifts only the part corresponding to the shift amount supplied from the address generation circuit 306and outputs the symbolic language inputted from the symbolic-language converter 301 to the switch 303 as a symbolic language of a byte unit. The switch 303 switched by the bit select signal which the address generation circuit 306 outputs is formed by the bitsupplies the symbolic language supplied from the barrel shifter 302 to RAM304and makes it memorize. The writing address at this time is specified from the address generation circuit 306. When a reading address is specified from the address generation circuit 306while the data (symbolic language) memorized by RAM304 is read and the latter converter 212 is suppliedif neededvia the switch 303RAM304 is supplied again and it memorizes.

[0112]The code length converter 305 determines the code length of syntax and an encoding parameter to the encoding parameter which are inputtedand outputs him to the address generation circuit 306. The address generation circuit 306 generates the shift amountthe bit select signalwriting addressor reading address mentioned above corresponding to the inputted code lengthand supplies them to barrel shifter 302switch 303or RAM304respectively.

[0113]As mentioned above,the history formatter 211 is constituted as what is called a variable-length-coding machinecarries out variable length coding of the inputted encoding parameterand outputs it.

[0114]Drawing 21 expresses the example of composition of the history decoder 203 which decodes the data by which history formatting was carried out as mentioned above. The data of the encoding parameter supplied from the converter 202 is supplied to RAM311and is memorized by this history decoder 203. The writing address at this time is supplied from the address generation circuit 315. The address generation circuit 315 generates a reading address to predetermined timingand supplies it to RAM311 again. At this timeRAM311 reads the data memorized in the reading addressand outputs it to the barrel shifter 312. Only the part corresponding to the shift amount which the address generation circuit 315 outputs shifts the data inputtedand outputs the barrel shifter 312 to the inverse code length converter 313 and

the inverse code word converter 314.

[0115]The name of the syntax of a stream with which the encoding parameter is arranged is supplied to the inverse code length converter 313 from the converter 202 again. Based on the syntax the inverse code length converter 313 asks for code length from the inputted data (symbolic language) and outputs the code length who asked to the address generation circuit 315.

[0116]The inverse code word converter 314 decodes the data supplied from the barrel shifter 312 based on syntax (forming an inverse code word) and outputs it to the encoding parameter multiplexer 103.

[0117]The inverse code word converter 314 extracts information (information required to determine a pause of a symbolic language) required to specify what kind of symbolic language is contained and outputs it to the address generation circuit 315. The address generation circuit 315 generates a shift amount and outputs it to the barrel shifter 312 while it generates a writing address and a reading address and outputs them to RAM 311 based on the code length inputted from this information and the inverse code length converter 313.

[0118]Drawing 22 expresses the example of composition of the converter 212. The buffer memory 320 arranged between the history formatter 211 and the converter 212 in this example 8-bit data is read from the reading address which the controller 326 outputs and D type flip-flop (D-FF) 321 is supplied and it is made as [ hold ]. And 8-bit D type flip-flop 322 is also supplied and the data read from D type flip-flop 321 is held while the staff circuit 323 is supplied. The 8-bit data read from D type flip-flop 322 is compounded with the 8-bit data read from D type flip-flop 321 and is supplied to the staff circuit 323 as 16-bit parallel data.

[0119]The staff circuit 323 inserts numerals "1" in the position of the signal (stuff position) which shows the staff position supplied from the controller 326 (carrying out stuffing) and outputs it to the barrel shifter 324 as a total of 17-bit data.

[0120]The barrel shifter 324 shifts the data inputted based on the signal (shift) which shows the shift amount supplied from the controller 326 extracts 8-bit data and outputs it to 8-bit D type flip-flop 325. The data held at D type flip-flop 325 is read from there and is supplied to the latter user-datum formatter 213 via the buffer memory 327. At this time the controller 326 generates a writing address with the data to output and supplies it to the buffer memory 327 which intervenes between the converter 212 and the user-datum formatter 213.

[0121]Drawing 23 expresses the example of composition of the staff circuit 323. The 16-bit data inputted from D type flip-flop 322 is inputted into the switch 331-16 thru/or the point of contact a of 331-1 respectively. The data of the switch which adjoins the MSB side (method of figure Nakagami) is supplied to the point of contact c of switch 331-i (i= 0 thru/or 15). For example the point of contact c of the switch 331-12. The 13th data is supplied from LSB currently supplied to the point of contact a of the switch 331-13 which adjoins the MSB side and the 14th data is supplied to the point of contact c of the switch 331-13 from the LSB side currently supplied to the point of contact a of the switch 331-13 which adjoins the MSB side.

[0122]However the point of contact a of the lower switch 331-0 is wide opened further from the switch 331-1 corresponding to LSB. Since the switch of a higher rank does not exist from the point of contact c of the switch 331-16 corresponding to MSB is opened wide.

[0123]Data "1" is supplied to each switch 331-0 thru/or the point of contact b of 331-16.

[0124]The decoder 332 corresponds to the signal stuff position which shows the position which

inserts data "1" supplied from the controller 326. One switch is changed to the point-of-contact b side the switch 331-0 thru/or among 331-16 the switch by the side of LSB is changed to the point-of-contact c side from it respectively and the switch by the side of MSB is made to be changed to the point-of-contact a side from it.

[0125] Drawing 23 shows the example in the case of inserting data "1" in the 13th from the LSB side. Therefore the switch 331-0 thru/or the switch 331-12 are changed to the point-of-contact c side by each in this case the switch 331-13 is changed to the point-of-contact b side and the switch 331-14 thru/or the switch 331-16 are changed to the point-of-contact a side.

[0126] By the above composition the converter 212 of drawing 22 will change 22-bit numerals into 23 bits and will output them.

[0127] Drawing 24 expresses the timing of the output data of each part of the converter 212 of drawing 22. If the controller 326 of the converter 212 generates a reading address (drawing 24 (A)) synchronizing with the clock of a byte unit from the buffer memory 320 the data corresponding to it will be read per byte and will once be held at D type flip-flop 321. And D type flip-flop 322 is supplied and the data (drawing 24 (B)) read from D type flip-flop 321 is held while the staff circuit 323 is supplied. The data held at D type flip-flop 322 is further read from there (drawing 24 (C)) and is supplied to the staff circuit 323.

[0128] Therefore the input (drawing 24 (D)) of the staff circuit 323 in [ in the timing of the reading address A1 it is considered as 1 byte of first data D0 and ] the timing of the next reading address A2 it becomes 1 byte of data D0 and 2 bytes of data which comprises 1 byte of the data D1 and becomes the data D1 and 2 bytes of data which comprises the data D2 in the timing of reading address A3 further.

[0129] The signal stuff position (drawing 24 (E)) which shows the position which inserts data "1" is supplied to the staff circuit 323 from the controller 326. The decoder 332 of the staff circuit 323 The switch 331-16 thru/or the inside of 331-0 The switch corresponding to this signal stuff position is switched to the point of contact b the switch by the side of LSB is switched to the point-of-contact c side from it and the switch by the side of MSB is further switched to the point-of-contact a side from it. Therefore since data "1" is inserted from the staff circuit 323 the data (drawing 24 (F)) in which data "1" was inserted in the position shown by the signal stuff position is outputted.

[0130] The barrel shift only of the quantity shown by the signal shift (drawing 24 (G)) to which the inputted data is supplied from the controller 326 is carried out and it outputs the barrel shifter 324 (drawing 24 (H)). Once this output is further held by D type flip-flop 325 it is outputted to the latter part (drawing 24 (I)).

[0131] It is 22-bit data next data "1" is inserted in the data outputted from D type flip-flop 325. Therefore between data "data of 1" and the next "1" even if all bits in the meantime are 0 the number with which the data of 0 continues is set to 22.

[0132] Drawing 25 expresses the example of composition of the converter 202. Although the composition which consists of D type flip-flop 341 thru/or the controller 346 of this converter 202 is the same composition as fundamentally as D type flip-flop 321 of the converter 212 thru/or the controller 326 shown in drawing 22 it replaces with the staff circuit 323 in the converter 212 and differs from the kick case to the converter 212 in that the DIRITO circuit 343 is inserted. Other composition is the same as that of the case in the converter 212 of drawing 22.

[0133]That is in this converter 202 that bit (data "1" inserted in the staff circuit 323 of drawing 22) is deleted for the DIRITO circuit 343 according to the signal delete position which shows the position which is a bit which the controller 346 outputs and to delete.

[0134]Other operations are the same as that of the case in the converter 212 of drawing 22.

[0135]Drawing 26 expresses the example of composition of the DIRITO circuit 343. In this example of composition 15 bits by the side of LSB of the 16-bit data inputted from D type flip-flop 342341 are supplied to the switch 351-0 corresponding respectively thru/or the point of contact a of 351-14. 1 bit of data by the side of MSB is supplied to the point of contact b of each switch. The decoder 352 deletes the bit specified by the signal delete position supplied from the controller 346 and is made as [ output / as 15-bit data ].

[0136]Drawing 26 shows the state DIRITO [ LSB / the 13th bit ]. Therefore the switch 351-0 thru/or the switch 351-11 are changed to the point-of-contact a side in this case and 12 bits from LSB to the 12th are chosen and outputted as they are. Since it changes to the point-of-contact b side respectively the 14th thru/or the 16th data are chosen as data of the 13th thru/or the 15th bit and the switch 351-12 thru/or 351-14 are outputted.

[0137]That the input of the staff circuit 323 of drawing 23 and the DIRITO circuit 343 of drawing 26 is 16 bits. Also in [ the input of the staff circuit 323 of the converter 212 of drawing 22 is 16 bits supplied from D type flip-flop 322321 respectively and ] the converter 202 of drawing 25. The input of the DIRITO circuit 343 is because it is considered as 16 bits by D type flip-flop 342341. By carrying out the barrel shift of the 17 bits which the staff circuit 323 outputs by the barrel shifter 324 in drawing 22 For example the same with choosing and outputting 8 bits eventually also in the converter 202 of drawing 25 the 15-bit data which the DIRITO circuit 343 outputs is used as 8-bit data when only the specified quantity carries out a barrel shift by the barrel shifter 344.

[0138]Drawing 27 expresses other examples of composition of the converter 212. In this example of composition the counter 361 counts the number which is a bit of 0 which continues among input data and is made as [ output / to the controller 326 / that counted result ]. The controller 326 outputs the signal stuff position to the staff circuit 323 when 22 bits of 0 which the counter 361 follows for example are counted. The controller 326 resets the counter 361 and makes the counter 361 count the number of the bits of 0 which continues again at this time.

[0139]Other composition and operations are the same as that of the case in drawing 22.

[0140]Drawing 28 expresses other examples of composition of the converter 202. In this example of composition the counter 371 counts the number of 0 which continues among input data and it is made as [ output / to the controller 346 / that counted result ]. When the counted value of the counter 371 amounts to 22 it resets the counter 371 and makes the counter 371 count the number of the again new bits of continuous 0 while the controller 346 outputs the signal delete position to the DIRITO circuit 343. Other composition is the same as that of the case in drawing 25.

[0141]Thus in this example of composition data "1" as a marker bit will be inserted and deleted based on a predetermined pattern (number with which data "0" continues).

[0142]The processing more efficient than the composition shown in drawing 22 and drawing 25 of the composition shown in drawing 27 and drawing 28 is attained. However the length after conversion will be dependent on the original hysteresis information.

[0143]Drawing 29 expresses the example of composition of the user-datum formatter 213. If

the controller 383 outputs a reading address to the buffer memory (not shown) arranged between the converter 212 and the user-datum formatter 213 in this example. The data read from there is supplied to the point-of-contact a side of the switch 382 of the user-datum formatter 213. Data required to generate user\_data() such as an user-datum start code and data ID is memorized by ROM 381. In predetermined timing the controller 313 changes the switch 382 to the point-of-contact a or point-of-contact b side chooses suitably the data memorized by ROM 381 or the data supplied from the converter 212 and outputs it. Thereby the data of a format of user\_data() is outputted to the coding equipment 106.

[0144] Although a graphic display is omitted, the user-datum decoder 201 is realizable by making it output input data via the switch which is read and deletes the inserted data from ROM 381 of drawing 29.

[0145] Drawing 30 shows the state where two or more transformer coders 101-1 thru/or 101-N are used being connected in series for example in image edit studio. Encoding parameter multiplexer 103-[] of each coding equipment 106-i (i = 1 thru/or N) ] i overwrites the newest encoding parameter that self used for the division where the oldest encoding parameter of the field for encoding parameters mentioned above is recorded. The encoding parameter for four latest generations corresponding to the same macro block (generation hysteresis information) will be recorded on the image data of baseband by this.

[0146] Encoder 121-[] of each coding equipment 106-i ] i (drawing 19) codes the video data supplied from the quantization circuit 57 in the variable-length-coding circuit 58 based on the encoding parameter used this time supplied from encoding parameter decollator 105-i. Thus the present encoding parameter multiplexes in the bit stream (for example picture\_header()) generated.

[0147] The variable-length-coding circuit 58 multiplexes again the user datum (generation hysteresis information is included) supplied from history coding equipment 107-i in the bit stream to output (it multiplexes not in embedding processing as shown in drawing 18 but in a bit stream). And the bit stream which coding equipment 106-i outputs is inputted into latter transformer coder 101- (i+1) via SDT 108-i.

[0148] Transformer coder 101-i and transformer coder 101- (i+1) are constituted as shown in drawing 15 respectively. Therefore the processing becomes being the same as that of the case where it explains with reference to drawing 15.

[0149] As coding using the history of the actual encoding parameter now what was coded as an I picture. When the history of the past encoding parameter is seen the case where they are P or B picture is looked for in the past to change into P or B picture and these histories exist a picture type is changed using parameters such as the motion vector. When there is no history in the past on the contrary change of the picture type which does not perform motion detection is given up. Even if it is a case where there is no history of course a picture type can be changed if motion detection is performed.

[0150] In the format shown in drawing 18 the encoding parameter for four generations was embedded but the parameter of each picture type of IP and B can be embedded. Drawing 31 shows the example of the format in this case. In this example the encoding parameter for one generation (picture hysteresis information) is recorded for every picture type when the same macro block is coded with change of a picture type in the past. Therefore the decoder 111 shown in drawing 16 and the encoder 121 shown in drawing 19 Now (newest) the encoding

parameter for one generation corresponding to I picture, P picture and B picture will be outputted and inputted instead of the encoding parameter of one generation two generations and three generations ago.

[0151] Since the field of  $Cb[1][x]$  and  $Cr[1][x]$  is not used in the case of this example, this invention is applicable also to the image data of 4:2:0 formats which does not have a field of  $Cb[1][x]$  and  $Cr[1][x]$ .

[0152] In the case of this example, the decoding device 102 takes out an encoding parameter simultaneously with decoding, judges a picture type, writes an encoding parameter in the place corresponding to the picture type of the picture signal, and outputs it to the encoding parameter (multiplexing) decollator 105. The encoding parameter decollator 105 separates an encoding parameter and it can perform recoding in consideration of the past encoding parameter inputted as the picture type to code from now on changing a picture type.

[0153] Next in each transformer coder 101, the processing which judges the picture type which can be changed is explained with reference to the flow chart of [drawing 32](#). Since the past motion vector is used, this processing is premised on performing without performing motion detection for change of the picture type in the transformer coder 101. Processing explained below is performed by the encoding parameter decollator 105.

[0154] In Step S1, the encoding parameter for one generation (picture hysteresis information) is inputted into the encoding parameter controller 122 for every picture type.

[0155] In Step S2, the encoding parameter decollator 105 judges whether an encoding parameter when it changes into picture hysteresis information at B picture exists. When judged with an encoding parameter when it changes into B picture existing in picture hysteresis information, it progresses to Step S3.

[0156] In Step S3, the encoding parameter decollator 105 judges whether an encoding parameter when it changes into picture hysteresis information at P picture exists. When judged with an encoding parameter when it changes into P picture existing in picture hysteresis information, it progresses to Step S4.

[0157] In Step S4, the encoding parameter decollator 105 judges that the picture types which can be changed are I picture, P picture and B picture.

[0158] In Step S3, when judged with an encoding parameter when it changes into picture hysteresis information at P picture not existing, it progresses to Step S5.

[0159] In Step S5, the encoding parameter decollator 105 judges that the picture types which can be changed are I picture and B picture. The encoding parameter decollator 105 is judged [ that it can change into P picture in false and ] by performing a special process (the backward prediction vector included in the hysteresis information of B picture is not used but only a forward prediction vector is used).

[0160] In Step S2, when judged with an encoding parameter when it changes into picture hysteresis information at B picture not existing, it progresses to Step S6.

[0161] In Step S6, the encoding parameter decollator 105 judges whether an encoding parameter when it changes into picture hysteresis information at P picture exists. When judged with an encoding parameter when it changes into P picture existing in picture hysteresis information, it progresses to Step S7.

[0162] In Step S7, the encoding parameter decollator 105 judges that the picture types which can be changed are I picture and P picture. The encoding parameter decollator 105 is judged [ that

it can change into B picture and ] by performing a special process (only the forward prediction vector included in hysteresis information at P picture is used).

[0163] In Step S6 when judged with an encoding parameter when it changes into picture hysteresis information at P picture not existing it progresses to Step S8. In Step S8 since a motion vector does not exist the encoding parameter decollator 105 judges that the picture type which can be changed is only I picture (it cannot change other than I picture since it is I picture).

[0164] After processing in step S9 the encoding parameter decollator 105 displays the picture type of step S4 S5 S7 and S8 which can be changed on a display (not shown) and notifies a user of it.

[0165] Drawing 33 shows the example of picture type change. The frame number from which change of a picture type constitutes GOP is changed. In the case of this example namely  $N=15$  (frame number  $N=15$  of GOP) From Long GOP (the 1st generation) which comprises a frame of  $M=3$  (I in GOP or appearance cycle  $M=3$  of P picture). It is changed into Short GOP (second generation) which comprises a frame of  $N=1$  and  $M=1$  and is again changed into  $N=15$  and Long GOP (third generation) which comprises a frame of  $M=3$ . The dashed line shows the boundary of GOP in the figure.

[0166] All the frames can change a picture type into I picture so that clearly from explanation of the picture type decision processing which was mentioned above and which can be changed when a picture type is changed into the second generation from the 1st generation. All the motion vectors calculated when video (the 0th generation) was changed into the 1st generation will be in the state (left behind) where it was saved at picture hysteresis information at the time of this picture type change. Next since the motion vector for every picture type when changed into the 1st generation from the 0th generation is saved when again changed into Long GOP (a picture type is changed into the third generation from the second generation) By reusing this image quality deterioration is suppressed and it becomes again possible to change into Long GOP.

[0167] Drawing 34 shows other examples of picture type change. In the case of this example from  $N=14$  and Long GOP (the 1st generation) which is  $M=2$ . It is changed into Short GOP (second generation) which is  $N=2$  and  $M=2$  the frame number which are  $N=1$  and  $M=1$  is further changed into Short GOP (third generation) of 1 and frame number  $N$  is changed into random GOP (fourth generation).

[0168] Also in this example it is saved till the conversion from the third generation of the motion vector for every picture type when changed into the 1st generation from the 0th generation to the fourth generation. Then as shown in drawing 34 even if it changes a picture type intricately image quality deterioration can be small suppressed by reusing the encoding parameter saved. If the quantizing scale of an encoding parameter saved is used effectively little coding of image quality deterioration is realizable.

[0169] Reuse of this quantizing scale is explained with reference to drawing 35. The predetermined frame is always changed into I picture from the 1st generation to the fourth generation and drawing 35 shows that only the bit rate is changed into 4Mbps 18Mbps or 50Mbps.

[0170] For example even if it carries out recoding with a fine quantizing scale with improvement in the speed of the bit rate in the case of the conversion to the second generation (18Mbps) from the 1st generation (4Mbps) image quality does not improve. It is because the data

quantized by the coarse quantization step in the past is not restored. Therefore as shown in drawing 35 even if the bit rate accelerates on the way the amount of information only increases and quantizing by a fine quantization step in connection with it does not lead to improvement in image quality. Therefore if it controls to maintain the past coarsest (large) quantizing scale there will be no futility and efficient coding will be attained.

[0171] As mentioned above when the bit rate is changed coding using the history of the past quantizing scale is dramatically effective.

[0172] This quantized control processing is explained with reference to the flow chart of drawing 36. In Step S11 the encoding parameter decollator 105 judges whether the encoding parameter of the picture type changed from now exists in the inputted picture hysteresis information. When judged with the encoding parameter of the picture type to change existing it progresses to Step S12.

[0173] In Step S12 the encoding parameter decollator 105 extracts a quantizing scale (Q\_history) from the encoding parameter used as contrast of picture hysteresis information.

[0174] In Step S13 the encoding parameter decollator 105 reads in the transmission buffer 59 candidate value Q\_feedback of the quantizing scale fed back to the quantization circuit 57.

[0175] In Step S14 the encoding parameter decollator 105 judges whether it is that Q\_history is larger (coarse) than Q\_feedback. When judged with Q\_history being larger than Q\_feedback it progresses to Step S15.

[0176] In Step S15 the encoding parameter decollator 105 outputs Q\_history to the quantization circuit 57 as a quantizing scale. The quantization circuit 57 performs quantization using Q\_history.

[0177] In Step S16 it is judged whether all the macro blocks contained in a frame were quantized. When judged with no macro blocks being quantized it returns to Step S13 and processing of Steps S13 thru/or S16 is repeated until all the macro blocks are quantized.

[0178] In Step S14 when Q\_history is judged to be \*\* (fine) which is not larger than Q\_feedback it progresses to Step S17.

[0179] In Step S17 the encoding parameter decollator 105 outputs Q\_feedback to the quantization circuit 57 as a quantizing scale. The quantization circuit 57 performs quantization using Q\_feedback.

[0180] In Step S11 when judged with the encoding parameter of the picture type to change not existing it progresses to Step S18.

[0181] In Step S18 the quantization circuit 57 receives candidate value Q\_feedback of the quantizing scale fed back from the transmission buffer 59.

[0182] In Step S19 the quantization circuit 57 performs quantization using Q\_feedback.

[0183] In Step S20 it is judged whether all the macro blocks contained in a frame were quantized. When judged with no macro blocks being quantized it returns to Step S18 and processing of Steps S18 thru/or S20 is repeated until all the macro blocks are quantized.

[0184] Although rough union is carried out and the decoding side and the numerals side made image data multiplex an encoding parameter and made it transmit in the inside of the transformer coder 101 in this embodiment as mentioned above as shown in drawing 37 the decoding device 102 and the coding equipment 106 are connected with the high speed bus 111 for encoding parameter transmission -- it may be made like (it couples closely).

[0185] Drawing 38 is a figure showing the syntax for decoding the video stream of MPEG. A



decoder extracts two or more meaningful data items (data element) from a bit stream by decoding an MPEG bit stream according to this syntax. As for the syntax explained below the function and conditional sentence are expressed with a thin printing type in a figure and the data element is expressed with \*\*\*\*\*. The data item is described by the mnemonic (Mnemonic) who shows the name bit length and its type and transmitting order.

[0186] First the function currently used in the syntax shown in this drawing 38 is explained.

[0187] A `next_start_code()` function is a function for looking for the start code described in the bit stream. Therefore in the syntax shown in this drawing 38 to the next of this `next_start_code()` function. Since the `sequence_header()` function and the `sequence_extension()` function are arranged in order to this bit stream. The data element defined by this `sequence_header()` function and a `sequence_extension()` function is described. Therefore at the time of decoding of a bit stream. By this `next_start_code()` function the start code (a kind of a data element) described at the head of the `sequence_header()` function and the `sequence_extension()` function is found out of a bit stream. It is based on it -- a `sequence_header()` function and a `sequence_extension()` function are found further and each data element defined by them is decoded.

[0188] A `sequence_header()` function. It is a function for defining the header data of the sequence layer of an MPEG bit stream and a `sequence_extension()` function is a function for defining the extended data of the sequence layer of an MPEG bit stream.

[0189] `do{}` arranged after the `sequence_extension()` function -- `{}` of `do [ while the conditions by which while syntax is defined by the while sentence are truth ] sentence` -- it is the syntax for extracting the data element described based on the inner function out of a data stream. That is by `do{while syntax while the conditions defined by the while sentence are truth}` decoding which extracts the data element described based on the function in `do` sentence out of a bit stream is performed.

[0190] The `nextbits()` function currently used for this while sentence is a function for comparing the bit or bit string which appears in a bit stream with the data element decoded next. In the example of the syntax of this drawing 38a `nextbits()` function. When `sequence_end_code` which shows the bit string in a bit stream and the end of a video sequence is compared and the bit string and `sequence_end_code` in a bit stream are not in agreement the conditions of this while sentence serve as truth. Therefore the `do{while syntax` arranged after the `sequence_extension()` function. While `sequence_end_code` which shows the end of a video sequence in a bit stream does not appear it is shown that the data element defined by the function in `do` sentence is described in a bit stream.

[0191] In the bit stream the data element defined by the `extension_and_user_data (0)` function is described by the next of each data element defined by the `sequence_extension()` function. This `extension_and_user_data (0)` function is a function for defining the extended data and the user datum of a sequence layer of an MPEG bit stream.

[0192] The `do{while syntax` arranged after this `extension_and_user_data (0)` function `{}` of `do [ while the conditions defined by the while sentence are truth ] sentence` -- it is a function for extracting the data element described based on the inner function out of a bit stream. The `nextbits()` function currently used in this while sentence is a function for judging coincidence with the bit or bit string which appears in a bit stream and `picture_start_code` or `group_start_code`. When the bit or bit string which appears in a bit stream and

picture\_start\_code or group\_start\_code is in agreement the conditions defined by the while sentence serve as truth. Therefore when picture\_start\_code or group\_start\_code appears in a bit stream this do{}while syntax. Since the code of the data element defined by the function in the start code next do sentence is described by discovering the start code shown by this picture\_start\_code or group\_start\_code the data element defined in do sentence can be extracted out of a bit stream.

[0193] In a bit stream if sentence described by the beginning of this do sentence shows the conditions of the case where group\_start\_code appears and is. When the conditions by this if sentence are truth in a bit stream The data element defined as the next of this group\_start\_code by the group\_of\_picture\_header (1) function and the extension\_and\_user\_data (1) function is described in order.

[0194] This group\_of\_picture\_header (1) function it is a function for defining the header data of the GOP layer of an MPEG bit stream -- an extension\_and\_user\_data (1) function It is a function for defining the extended data (extension\_data) and the user datum (user\_data) of a GOP layer of an MPEG bit stream.

[0195] To the next of the data element defined by the group\_of\_picture\_header (1) function and the extension\_and\_user\_data (1) function in this bit stream. The data element defined by the picture\_header() function and the picture\_coding\_extension() function is described. Of course when the conditions of if sentence explained previously do not serve as truth. Since the data element defined by the group\_of\_picture\_header (1) function and the extension\_and\_user\_data (1) function is not described To the next of the data element defined by the extension\_and\_user\_data (0) function. The data element defined by the picture\_header() function and the picture\_coding\_extension() function is described.

[0196] This picture\_header() function it is a function for defining the header data of the picture layer of an MPEG bit stream -- a picture\_coding\_extension() function is a function for defining the 1st extended data of the picture layer of an MPEG bit stream.

[0197] The following while sentence is a function for performing conditional judgment of the following if sentence while the conditions defined by this while sentence are truth. The next bits() function currently used in this while sentence The bit string which appears in a bit stream and the bit string which is a function for judging coincidence with extension\_start\_code or user\_data\_start\_code and appears in a bit stream When extension\_start\_code or user\_data\_start\_code is in agreement the conditions defined by this while sentence serve as truth.

[0198] 1st if sentence is a function for judging coincidence with the bit string and extension\_start\_code which appear in a bit stream. When the bit string and 32-bit extension\_start\_code which appear in a bit stream are in agreement It is shown that the data element defined by the next of extension\_start\_code by an extension\_data (2) function in a bit stream is described.

[0199] 2nd if sentence is syntax for judging coincidence with the bit string and user\_data\_start\_code which appear in a bit stream When the bit string and 32-bit user\_data\_start\_code which appear in a bit stream are in agreement conditional judgment of 3rd if sentence is performed. This user\_data\_start\_code is a start code for the start of the user data area of the picture layer of an MPEG bit stream to be shown.

[0200] 3rd if sentence is syntax for judging coincidence with the bit string and History\_Data\_ID

which appear in a bit stream. When the bit string which appears in a bit stream and this 8-bit History\_Data\_ID are in agreement in the user data area of the picture layer of this MPEG bit stream, it is shown that there is a code shown by this 8-bit History\_Data\_ID next to the data element defined by a converted\_history\_stream() function is described.

[0201] A converted\_history\_stream() function is a function for describing the hysteresis information and historical data for transmitting all the encoding parameters used at the time of MPEG coding. The details of the data element defined by this converted\_history\_stream() function are mentioned later. This History\_Data\_ID is a start code for the head where these hysteresis information and historical data that were described by the user data area of the picture layer of an MPEG bit stream are described to be shown.

[0202] An else sentence is syntax for that conditions are non-truth to be shown in 3rd if sentence. Therefore in the user data area of the picture layer of this MPEG bit stream, when the data element defined by the converted\_history\_stream() function is not described, the data element defined by the user\_data() function is described.

[0203] A picture\_data() function is a user datum of the picture layer of an MPEG bit stream, next is a function for describing the data element about a slice layer and a macro block layer. Usually, the data element shown by this picture\_data() function, although described by the next of the data element defined by the data element or user\_data() function defined by the converted\_history\_stream() function described by the user data area of the picture layer of a bit stream, when extension\_start\_code or user\_data\_start\_code does not exist in the bit stream which shows the data element of a picture layer, described by the next of the data element shown by this picture\_data() function, and the data element defined by a picture\_coding\_extension() function.

[0204] After the data element shown by this picture\_data() function, the data element defined by the sequence\_header() function and the sequence\_extension() function is arranged in order. The data element described by this sequence\_header() function and the sequence\_extension() function is completely the same as the data element described by the sequence\_header() function described at the head of the sequence of a video stream, and the sequence\_extension() function. Thus, the reason for describing the same data in a stream, when reception is started by the bit stream receiving set side from the middle (for example, bit stream portion corresponding to a picture layer) of a data stream, is for preventing that it becomes impossible to receive the data of a sequence layer, and it becomes impossible to decode a stream.

[0205] The next of the data element defined by the sequence\_header() function and sequence\_extension() function of this last is 32-bit sequence\_end\_code which shows the end of a sequence is described by the last of the data stream.

[0206] When the outline of the fundamental composition of the above syntax is shown, it comes to be shown in drawing 39.

[0207] Next, the history stream defined by the converted\_history\_stream() function is explained.

[0208] This converted\_history\_stream() is a function for inserting in the user data area of the picture layer of MPEG the history stream which shows hysteresis information. In order that the meaning of "converted" may prevent a start emulation, it means being the stream which performed the conversion process which inserts a marker bit (1 bit) every at least 22 bits of the history stream which comprises historical data which should be inserted in user area.

[0209] This converted\_history\_stream() is described by in the form of [ of explaining below ]

either a fixed-length history stream (drawing 40 thru/or drawing 46) or a variable-length history stream (drawing 47). When a fixed-length history stream is chosen as the encoder side there is a merit that the circuit and software for decoding each data element from a history stream to the decoder side become easy. On the other hand when a variable-length history stream is chosen as the encoder side since the hysteresis information (data element) described by the user area of a picture layer in an encoder can be chosen arbitrarily if needed the data rate of the whole bit stream which could lessen data volume of the history stream and was coded as a result can be reduced.

[0210] "Hysteresis information" the "historical data" and the "history parameter" which are explained in this invention are an encoding parameter (or data element) used in the past coding processing and are not an encoding parameter used in the present coding processing (final stage). for example-- coding and transmitting a certain picture by I picture in the 1st-generation coding processing -- the next -- in coding processing of the second generation. Shortly it codes as a P picture. This picture is transmitted and the example which codes and transmits this picture by B picture is further given and explained in coding processing of the third generation. The encoding parameter used in coding processing of the third generation is described by the prescribed position of the sequence layer of the encoded bit streams generated in coding processing of the third generation. A GOP layer, the picture layer, the slice layer, and the macro block layer. The encoding parameter used on the other hand in the coding processing of the 1st generation and the second generation which is the past coding processing. If described by the sequence layer and GOP layer, the encoding parameter used in coding processing of the third generation is described to be there is nothing and according to the already explained syntax it is described by the user data area of a picture layer as hysteresis information of an encoding parameter.

[0211] First fixed-length history stream syntax is explained with reference to drawing 40 thru/or drawing 46.

[0212] In the user area of the picture layer of the bit stream generated in coding processing of a final stage (for example third generation). First the encoding parameter about the sequence header of the sequence layer currently used in the past (for example the 1st generation and the second generation) coding processing is inserted as a history stream. Hysteresis informations such as a sequence header etc. of the sequence layer of the bit stream generated in the past coding processing should be noticed about the point of not being inserted in the sequence header of the sequence layer of the bit stream generated in coding processing of a final stage.

[0213] The data element about the sequence header used by the past coding processing: sequence\_header\_code, sequence\_header\_present\_flag, horizontal\_size\_value, vertical\_size\_value, aspect\_ratio\_information, frame\_rate\_code, bit\_rate\_value, marker\_bit, VBV\_buffer\_size\_value, constrained\_parameter\_flag, load\_intra\_quantizer\_matrix. It comprises

intra\_quantizer\_matrix, load\_non\_intra\_quantizer\_matrix, non\_intra\_quantizer\_matrix etc.  
 [0214] sequence\_header\_code is data showing the start synchronization code of a sequence layer. sequence\_header\_present\_flag is data in which it is shown whether the data in sequence\_header is effective or invalid. horizontal\_size\_value is data which comprises 12 bits of low ranks of the horizontal pixel number of a picture. vertical\_size\_value is data which consists of 12 bits of low ranks of the line number of the length of a picture.

aspect\_ratio\_information is data showing the aspect ratio (aspect ratio) or display screen aspect ratio of a pixel. frame\_rate\_code is data showing the display period of a picture.

[0215]bit\_rate\_value is 18 bits (it revalues per 400bsp) of low rank data of the bit rate for the restriction to a generation bit amount. marker\_bit is bit data inserted in order to prevent a start code emulation. VBV\_buffer\_size\_value is low rank 10 bit data of the value which determines the size of the virtual buffer for generated code amount control (video buffer verifier).

constrained\_parameter\_flag is data in which it is shown that each parameter is less than restriction. load\_intra\_quantizer\_matrix is data in which existence of the quantizing-matrix data for the intra MB is shown. intra\_quantizer\_matrix is data in which the value of the quantizing matrix for the intra MB is shown. load\_non\_intra\_quantizer\_matrix is data in which existence of the quantizing-matrix data for the non-intra MB is shown. non\_intra\_quantizer\_matrix is data showing the value of the quantizing matrix for the non-intra MB.

[0216]Next the data element which expresses the sequence extension of the sequence layer used in the past coding processing to the user area of the picture layer of the bit stream generated in coding processing of a final stage is described as a history stream.

[0217]The data element showing the sequence extension used by coding processing of this past extension\_start\_code extension\_start\_code\_identifier sequence\_extension\_present\_flag profile\_and\_level\_indication progressive\_sequence chroma\_format horizontal\_size\_extension vertical\_size\_extension bit\_rate\_extension low\_delay frame\_rate\_extension\_n and frame\_rate\_extension\_d.

[0218]extension\_start\_code is data showing the start synchronization code of extension data. extension\_start\_code\_identifier is data in which it is shown which extended data is sent. sequence\_extension\_present\_flag is data in which it is shown whether the data within a sequence extension is effective or invalid. profile\_and\_level\_indication is data for specifying the profile and level of a video data. progressive\_sequence is data in which it is shown that a video data is sequential scanning. chroma\_format is data for specifying the color difference format of a video data.

[0219]horizontal\_size\_extension is top 2-bit data added to horizontal\_size\_value of a sequence header. vertical\_size\_extension is top 2-bit data added to vertical\_size\_value of a sequence header. bit\_rate\_extension is top 12-bit data added to bit\_rate\_value of a sequence header. vbv\_buffer\_size\_extension is top 8-bit data added to vbv\_buffer\_size\_value of a sequence header. low\_delay is data in which it is shown that B picture is not included. frame\_rate\_extension\_n is data for obtaining a frame rate combining frame\_rate\_code of a sequence header. frame\_rate\_extension\_d is data for obtaining a frame rate combining frame\_rate\_code of a sequence header.

[0220]Then the data element which expresses the sequence display extension of the sequence layer used in the past coding processing to the user area of the picture layer of a bit stream is described as a history stream.

[0221]The data element described as this sequence display extension extension\_start\_code extension\_start\_code\_identifier sequence\_display\_extension\_present\_flag video\_format color\_description is data in which it is shown whether the data within a sequence display extension is effective or invalid. profile\_and\_level\_indication is data for specifying the profile and level of a video data. progressive\_sequence is data in which it is shown that a video data is sequential scanning. chroma\_format is data for specifying the color difference format of a video data.

[0222]extension\_start\_code is data showing the start synchronization code of extension data.

extension\_start\_code\_identifier is a code which shows which extended data is sent. sequence\_display\_extension\_present\_flag is data in which it is shown whether the data element within a sequence display extension is effective or invalid. video\_format is data showing the video image format of the HARASHIN item. color\_description is data in which it is shown that there is detailed data of a color space. color\_primaries is data in which the details of the color characteristic of the HARASHIN item are shown. transfer\_characteristics is data in which the details of how photoelectric conversion was performed are shown. matrix\_coefficients is data in which the details of how the HARASHIN item was changed from the three primary colors of light are shown. display\_horizontal\_size is data showing the active region (horizontal size) of the display to mean. display\_vertical\_size is data showing the active region (vertical size) of the display to mean.

[0223]Then to the user area of the picture layer of the bit stream generated in coding processing of a final stage. The macro block assignment data (macroblock\_assignment\_in\_user\_data) in which the topology of the macro block generated in the past coding processing is shown is described as a history stream.

[0224]macroblock\_assignment\_in\_user\_data which shows the topology of this macro block comprises data elements such as macroblock\_assignment\_present\_flag, v\_phase and h\_phase.

[0225]This macroblock\_assignment\_present\_flag is data in which it is shown whether the data element in macroblock\_assignment\_in\_user\_data is effective or invalid. v\_phase is data in which the topology of the perpendicular direction at the time of starting a macro block from image data is shown. h\_phase is data in which the horizontal topology at the time of starting a macro block from image data is shown.

[0226]Then the data element which expresses the GOP header of the GOP layer used in the past coding processing to the user area of the picture layer of the bit stream generated by coding processing of the final stage is described as a history stream.

[0227]The data element showing this GOP header comprises

group\_start\_code, group\_of\_picture\_header\_present\_flag, time\_code, closed\_gop and broken\_link.

[0228]group\_start\_code is data in which the start synchronization code of a GOP layer is shown. It is data in which it is shown whether the data element in

group\_of\_picture\_header\_present\_flag and group\_of\_picture\_header is effective or invalid. time\_code is a time code which shows the time from the head of the sequence of the leading picture of GOP. closed\_gop is flag data in which a thing with a picture refreshable independently of other GOP(s) in GOP is shown. broken\_link is flag data in which it is shown that B picture of the head in GOP cannot be correctly reproduced because of edit etc.

[0229]Then the data element which expresses the picture header of the picture layer used in the past coding processing to the user area of the picture layer of the bit stream generated by coding processing of the final stage is described as a history stream.

[0230]The data element about this picture header picture\_start\_code, temporal\_reference, and comprises

picture\_coding\_type, vbv\_delay, full\_pel\_forward\_vector, forward\_f\_code, full\_pel\_backward\_vector and backward\_f\_code.

[0231]Specifically picture\_start\_code is data showing the start synchronization code of a picture layer. temporal\_reference is data reset at the head of GOP by the number which shows the display order of a picture. picture\_coding\_type is data in which a picture type is shown.

vbv\_delay is data in which the initial state of the virtual buffer at the time of random access is shown. full\_pel\_forward\_vector is data which the accuracy of a forward direction motion vector shows an integer unit or a half a pixel unit. forward\_f\_code is data showing a forward direction motion vector search range. full\_pel\_backward\_vector is data which the accuracy of an opposite direction motion vector shows an integer unit or a half a pixel unit. backward\_f\_code is data showing an opposite direction motion vector search range.

[0232] Then the picture coding extension of the picture layer used in the past coding processing is described by the user area of the picture layer of the bit stream generated by coding processing of the final stage as a history stream.

[0233] The data element about this picture coding

extension\_start\_code extension\_start\_code\_identifier f\_code [0][0] f\_code [0] and [1] f\_code [1][0] f\_code

[1][1] intra\_dc\_precision picture\_structure top\_field\_first frame\_predictive\_frame\_dct concealment\_motion\_vectors q\_scale\_type intra\_vlc\_format alternate\_scan repeat\_firt\_field chroma\_420\_type pelt comprises

progressive\_frame composite\_display\_flag v\_axis field\_sequence sub\_carrier burst\_amplitude and sub\_carrier\_phase.

[0234] extension\_start\_code is a start code which shows the start of the extension data of a picture layer. extension\_start\_code\_identifier is a code which shows which extended data is sent. f\_code [0] and [0] are data showing the level motion vector search range of the direction of a forward. f\_code [0] and [1] are data showing the vertical motion vector search range of the direction of a forward. f\_code [1] and [0] are data showing the level motion vector search range of the backward direction. f\_code [1] and [1] are data showing the vertical motion vector search range of the backward direction.

[0235] intra\_dc\_precision is data showing the accuracy of a DC coefficient. picture\_structure is data in which a frame structure or a field structure is shown. In the case of a field structure they are the higher rank field the low rank field or data set and shown. In the case of a frame structure top\_field\_first is data which the first field shows a higher rank or a low rank. frame\_predictive\_frame\_dct is data in which it is shown in the case of a frame structure that prediction of frame mode DCT is only a frame mode. concealment\_motion\_vectors is data in which it is shown that the motion vector for concealing a transmission error is attached to the Intra macro block.

[0236] q\_scale\_type is data in which it is shown whether a linear quantization scale is used or a nonlinear quantization scale is used. intra\_vlc\_format is data in which it is shown whether another two-dimensional VLC is used for the Intra macro block. alternate\_scan is data showing selection of whether a zigzag scan is used or to use an alternate scan. repeat\_firt\_field is data used 2:3 when pulldown. When the signal format of chroma\_420\_type is 4:2:0 they are the same value as following progressive\_frame and data which expresses 0 when that is not right. progressive\_frame is data in which it is shown whether this picture can be scanned sequentially. composite\_display\_flag is data in which it is shown whether the source signal was a composite signal.

[0237] v\_axis is data in which a source signal is used in the case of PAL. field\_sequence is data in which a source signal is used in the case of PAL. sub\_carrier is data in which a source signal is used in the case of PAL. burst\_amplitude is data in which a source signal is used in the case of

PAL. sub\_carrier\_phase is data in which a source signal is used in the case of PAL.

[0238]Then the quantizing-matrix extension used in the past coding processing is described by the user area of the picture layer of the bit stream generated by coding processing of the final stage as a history stream.

[0239]The data element about this quantizing-matrix

extensionextension\_start\_codeextension\_start\_code\_identifierquant\_matrix\_extension\_present\_flagload\_intra\_quantizer\_matrixintra\_quantizer\_matrix

[64]load\_non\_intra\_quantizer\_matrixnon\_intra\_quantizer\_matrix

[64]load\_chroma\_intra\_quantizer\_matrixIt comprises chroma\_intra\_quantizer\_matrix

[64]load\_chroma\_non\_intra\_quantizer\_matrixand chroma\_non\_intra\_quantizer\_matrix [64].

[0240]extension\_start\_code is a start code which shows the start of this quantizing-matrix extension. extension\_start\_code\_identifier is a code which shows which extended data is sent. quant\_matrix\_extension\_present\_flag is data for whether the data element within this quantizing-matrix extension is effective or invalid to be shown. load\_intra\_quantizer\_matrix is data in which existence of the quantization matrix data for Intra macro blocks is shown. intra\_quantizer\_matrix is data in which the value of the quantizing matrix for Intra macro blocks is shown.

[0241]load\_non\_intra\_quantizer\_matrix is data in which existence of the quantization matrix data for non-Intra macro blocks is shown. non\_intra\_quantizer\_matrix is data showing the value of the quantizing matrix for non-Intra macro blocks. load\_chroma\_intra\_quantizer\_matrix is data in which existence of the quantizing-matrix data for color difference Intra macro blocks is shown. chroma\_intra\_quantizer\_matrix is data in which the value of the quantizing matrix for color difference Intra macro blocks is shown. load\_chroma\_non\_intra\_quantizer\_matrix is data in which existence of the quantizing-matrix data for color difference non-Intra macro blocks is shown. chroma\_non\_intra\_quantizer\_matrix is data in which the value of the quantizing matrix for color difference non-Intra macro blocks is shown.

[0242]Then the copyright extension used in the past coding processing is described by the user area of the picture layer of the bit stream generated by coding processing of the final stage as a history stream.

[0243]The data element about this copyright

extensionextension\_start\_codeextension\_start\_code\_identifiercopyright\_extension\_present\_flagIt comprises copyright\_flagcopyright\_identifieroriginal\_or\_copycopyright\_number\_1copyright\_number\_2and copyright\_number\_3.

[0244]extension\_start\_code is a start \*\*\*\* start code of a copyright extension. It is a code which shows whether the extension data of an extension\_start\_code\_identifier throat is sent. copyright\_extension\_present\_flag is data for whether the data element within this copyright extension is effective or invalid to be shown. copyright\_flag shows whether the right of a copy is granted to the coded video data to a following copyright extension or sequence end.

[0245]copyright\_identifier is data for identifying the registration agency of the right of a copy specified by ISO/IEC JTC/SC29. original\_or\_copy is data in which it is shown whether the data in a bit stream is original data or it is copy data. copyright\_number\_1 is data showing the bits 44-63 of a copyright number. copyright\_number\_2 is data showing the bits 22-43 of a copyright number. copyright\_number\_3 is data showing the bits 0-21 of a copyright number.



[0246]Then to the user area of the picture layer of the bit stream generated by coding processing of the final stage. The picture display extension (picture\_display\_extension) used in the past coding processing is described as a history stream.

[0247]The data element showing this picture display extensionextension\_start\_codeextension\_start\_code\_identifierpicture\_display\_extension\_present\_flagframe\_center\_horizontal\_offset\_1frame\_center\_vertical\_offset\_1frame\_center\_horizontal\_offset\_2frame\_center\_vertical\_offset\_2frame\_center\_horizontal\_offset\_3and frame\_center\_vertical\_offset\_3.

[0248]extension\_start\_code is a start code for the start of a picture display extension to be shown. extension\_start\_code\_identifier is a code which shows which extended data is sent. picture\_display\_extension\_present\_flag is data in which it is shown whether the data element within a picture display extension is effective or invalid. frame\_center\_horizontal\_offset is data in which horizontal offset of display area is shownand can be defined to three offset values. frame\_center\_vertical\_offset is data in which vertical offset is shownand can define display area to three offset values.

[0249]The user datum used in coding processing of the hysteresis information which expresses the already explained picture display extension to the user area of the picture layer of the bit stream generated in coding processing of a final stagenext the past is described as a history stream.

[0250]The information about the macro block layer used in the past coding processing is described as a history stream by the next of this user datum.

[0251]The information about this macro block layer macroblock\_address\_hThe data element about the position of macro blockssuch as macroblock\_address\_vslice\_header\_present\_flagand skipped\_macroblock\_flagmacroblock\_quantmacroblock\_motion\_forwardmacroblock\_motion\_backwardmacroblock\_patternmacroblock\_intraspatial\_temporal\_weight\_code\_flagThe data element about macro block modessuch as frame\_motion\_type and dct\_typeThe data element about quantization step control of quantiser\_scale\_code etc.[PMV [0][0][0]PMV [0] and [0]1]motion\_vertical\_field\_select [0] and [0]PMV [0][1] and [0]PMV [0][1] and [1]motion\_vertical\_field\_select [0][1][PMV [1][0][0]PMV [1] and [0]1]motion\_vertical\_field\_select [1][0]The data element about motion compensationssuch as PMV [1][1][0]PMV [1][1] and [1]motion\_vertical\_field\_select [1][1]It comprises a data element about macro block patternssuch as coded\_block\_patternand a data element about generated code amountssuch as num\_mv\_bitsnum\_coef\_bitsand num\_other\_bits.

[0252]The data element about a macro block layer is explained in detail below.

[0253]macroblock\_address\_h is data for defining the horizontal absolute position of the present macro block. macroblock\_address\_v is data for defining the absolute position of the perpendicular direction of the present macro block. This macro block is a head of a slice layerand slice\_header\_present\_flag is data in which it is shown whether it is accompanied by a slice header. skipped\_macroblock\_flag is data in which it is shown whether this macro block is skipped in decoding processingand is \*\*.

[0254]macroblock\_quant is data led from the macro block type (macroblock\_type) shown in [drawing 65](#) thru/[or drawing 67](#) mentioned laterand is data in which it is shown whether quantiser\_scale\_code appears in a bit stream. macroblock\_motion\_forward is data led from the

macro block type shown in drawing 65 thru/or drawing 67 and is data used by decoding processing. macroblock\_motion\_backward is data led from the macro block type shown in drawing 65 thru/or drawing 67 and is data used by decoding processing. macroblock\_pattern is data led from the macro block type shown in drawing 65 thru/or drawing 67 and is data in which it is shown whether coded\_block\_pattern appears in a bit stream.

[0255]macroblock\_intra is data led from the macro block type shown in drawing 65 thru/or drawing 67 and is data used by decoding processing. spatial\_temporal\_weight\_code\_flag is data led from the macro block type shown in drawing 65 thru/or drawing 67 spatial\_temporal\_weight\_code which shows the rise sampling of a low order layer picture with time scalability is data in which it is shown whether it exists in a bit stream.

[0256]frame\_motion\_type is a 2-bit code which shows the prediction type of the macro block of a frame. It is "00" if an estimated vector is a prediction type of a field base in two pieces, it is "11" if it is "10" if it is "01" if an estimated vector is a prediction type of a field base in one piece and an estimated vector is a prediction type of a frame base in one piece and an estimated vector is a prediction type of a DIARU prime in one piece. field\_motion\_type is a 2-bit code which shows the motion prediction of the macro block of the field. It is "11" if it is "10" if it is "01" if an estimated vector is a prediction type of a field base in one piece and an estimated vector is a prediction type of an 18x8 macro-block base in two pieces and an estimated vector is a prediction type of a DIARU prime in one piece. dct\_type is data which DCT shows frame DCT mode and field DCT mode. quantiser\_scale\_code is data in which the quantization step size of a macro block is shown.

[0257]Next the data element about a motion vector is explained. A motion vector is coded as difference about the vector coded previously in order to decrease a motion vector required at the time of decoding. In order to decode a motion vector the decoder must maintain the motion vector predicted value (level respectively and accompanied by a vertical component) of four pieces. This prediction motion vector is expressed as PMV [r] and [s] [v]. [r] whether the motion vector in a macro block is the 1st vector. It is a flag which shows whether it is the 2nd vector when the vector in a macro block is the 1st vector it is set to "0" and it is set to "1" when the vector in a macro block is the 2nd vector. [s] is a flag which shows whether it is front and whether the direction of the motion vector in a macro block is the back in the case of a front motion vector is set to "0" and in the case of a back motion vector is set to "1." [v] It is a flag which shows whether it is horizontal and perpendicular and in the case of a horizontal component the ingredient of the vector in a macro block is set to "0" and in the case of a perpendicular direction ingredient is set to "1."

[0258]Therefore PMV [0][0] and [0] express the data of the horizontal component of the motion vector of the front of the 1st vector and PMV [0][0] and [1] Express the data of the perpendicular direction ingredient of the motion vector of the front of the 1st vector and PMV [0][1] and [0] Express the data of the horizontal component of the motion vector of the back of the 1st vector and PMV [0][1] and [1] the data of the perpendicular direction ingredient of the motion vector of the back of the 1st vector is expressed -- PMV [1][0] and [0] Express the data of the horizontal component of the motion vector of the front of the 2nd vector and PMV [1][0] and [1] the data of the perpendicular direction ingredient of the motion vector of the front of the 2nd vector is expressed -- PMV [1][1] and [0] Expressing the data of the horizontal component of the motion vector of the back of the 2nd vector PMV [1][1] and [1] express the data of the

perpendicular direction ingredient of the motion vector of the back of the 2nd vector.

[0259]motion\_vertical\_field\_select [r] and [s] are data which shows whether which reference field is used in the form of prediction. When this motion\_vertical\_field\_select [r] and [s] are "0" using a top reference field and using a bottom product reference field in the case of "1" is shown.

[0260]motion\_vertical\_field\_select [0] and [0] [therefore] The reference field at the time of generating the motion vector of the front of the 1st vector is shown and motion\_vertical\_field\_select [0] and [1] The reference field at the time of generating the motion vector of the back of the 1st vector is shown and motion\_vertical\_field\_select [1] and [0] The reference field at the time of generating the motion vector of the front of the 2nd vector is shown and motion\_vertical\_field\_select [1] and [1] show the reference field at the time of generating the motion vector of the back of the 2nd vector.

[0261]coded\_block\_pattern is variable-length data in which it is shown which DCT blocks have a significant coefficient (un-0 coefficient) among two or more DCT blocks which store a DCT coefficient. num\_mv\_bits is data in which the code amount of the motion vector in a macro block is shown. num\_coef\_bits is data in which the code amount of the DCT coefficient in a macro block is shown. num\_other\_bits is a code amount of a macro block and is data in which code amounts other than a motion vector and a DCT coefficient are shown.

[0262]Next the syntax for decoding each data element from a variable-length history stream is explained with reference to [drawing 47](#) thru/or [drawing 64](#).

[0263]This variable-length history stream A next\_start\_code() function A sequence\_header() function a sequence\_extension() function An extension\_and\_user\_data (0) function a group\_of\_picture\_header() function An extension\_and\_user\_data (1) function a picture\_header() function It is constituted by the data element defined by the picture\_coding\_extension() function the extension\_and\_user\_data (2) function and the picture\_data() function.

[0264]A next\_start\_code() function Since it is a function for looking for the start code which exists in a bit stream at the very head of a history stream It is the data element used in coding processing of the past as shown in [drawing 48](#) and the data element defined by the sequence\_header() function is described.

[0265]The data element defined by the sequence\_header() function sequence\_header\_code sequence\_header\_present\_flag horizontal\_size\_value vertical\_size\_value aspect\_ratio\_information frame\_rate\_code bit\_rate\_value marker\_bit VBV\_buffer\_size\_value constrained\_parameter\_flag load\_intra\_quantizer\_matrix They are intra\_quantizer\_matrix load\_non\_intra\_quantizer\_matrix non\_intra\_quantizer\_matrix etc.

[0266]sequence\_header\_code is data showing the start synchronization code of a sequence layer. sequence\_header\_present\_flag is data in which it is shown whether the data in sequence\_header is effective or invalid. horizontal\_size\_value is data which comprises 12 bits of low ranks of the horizontal pixel number of a picture. vertical\_size\_value is data which consists of 12 bits of low ranks of the line number of the length of a picture. aspect\_ratio\_information is data showing the aspect ratio (aspect ratio) or display screen aspect ratio of a pixel. frame\_rate\_code is data showing the display period of a picture. bit\_rate\_value is 18 bits (it revalues per 400bsp) of low rank data of the bit rate for the restriction to a generation bit amount.

[0267]marker\_bit is bit data inserted in order to prevent a start code emulation.

VBV\_buffer\_size\_value is low rank 10 bit data of the value which determines the size of the virtual buffer for generated code amount control (video buffer verifier).

constrained\_parameter\_flag is data in which it is shown that each parameter is less than

restriction. load\_intra\_quantizer\_matrix is data in which existence of the quantizing-matrix data for the intra MB is shown. intra\_quantizer\_matrix is data in which the value of the quantizing matrix for the intra MB is shown. load\_non\_intra\_quantizer\_matrix is data in which existence of the quantizing-matrix data for the non-intra MB is shown. non\_intra\_quantizer\_matrix is data showing the value of the quantizing matrix for the non-intra MB.

[0268]The data element defined as the next of the data element defined by the sequence\_header() function by the sequence\_extension() function as shown by drawing 49 is described as a history stream.

[0269]With the data element defined by the sequence\_extension() function.

extension\_start\_codeextension\_start\_code\_identifiersequence\_extension\_present\_flagprofile\_and\_level\_indicationprogressive\_sequencechroma\_formathorizontal\_size\_extensionvertical\_size\_extensionbit\_rate\_extensionThey are data elementssuch as

vbv\_buffer\_size\_extensionlow\_delayframe\_rate\_extension\_nand frame\_rate\_extension\_d.

[0270]extension\_start\_code is data showing the start synchronization code of extension data.

extension\_start\_code\_identifier is data in which it is shown which extended data is sent.

sequence\_extension\_present\_flag is SUDETA which shows whether the data within a sequence extension is effective or invalid. profile\_and\_level\_indication is data for specifying the profile and level of a video data. progressive\_sequence is data in which it is shown that a video data is sequential scanning. chroma\_format is data for specifying the color difference format of a video data. horizontal\_size\_extension is top 2-bit data added to horizontal\_size\_value of a sequence header. vertical\_size\_extension is top 2-bit data which is a sequence header and which vertical\_size\_value adds. bit\_rate\_extension is top 12-bit data added to bit\_rate\_value of a sequence header. vbv\_buffer\_size\_extension is top 8-bit data added to vbv\_buffer\_size\_value of a sequence header.

[0271]low\_delay is data in which it is shown that B picture is not included.

frame\_rate\_extension\_n is data for obtaining a frame rate combining frame\_rate\_code of a sequence header. frame\_rate\_extension\_d is data for obtaining a frame rate combining frame\_rate\_code of a sequence header.

[0272]The data element defined as the next of the data element defined by the

sequence\_extension() function by the extension\_and\_user\_data (0) function as shown in drawing 50 is described as a history stream. An extension\_and\_user\_data(i) functionWhen "i" is except twothe data element defined by an extension\_data() function describes only the data element defined by a user\_data() function as a history streamwithout describing. Thereforeonly the data element defined by the extension\_and\_user\_data (0) function and a user\_data() function is described as a history stream.

[0273]A user\_data() function describes a user datum as a history stream based on syntax as shown in drawing 51.

[0274]In the next of the data element defined by the extension\_and\_user\_data (0) function.

The data element defined by the group\_of\_picture\_header() function as shown in drawing 52and the data element defined by an extension\_and\_user\_data (1) function are described as a

history stream. However only when group\_start\_code which shows the start code of a GOP layer in a history stream is described. The data element defined by the group\_of\_picture\_header() function and the data element defined by an extension\_and\_user\_data(1) function are described.

[0275] The data element defined by the group\_of\_picture\_header() function it comprises group\_start\_code, group\_of\_picture\_header\_present\_flag, time\_code, closed\_gop and broken\_link.

[0276] group\_start\_code is data in which the start synchronization code of a GOP layer is shown. It is data in which it is shown whether the data element in

group\_of\_picture\_header\_present\_flag and group\_of\_picture\_header is effective or invalid. time\_code is a time code which shows the time from the head of the sequence of the leading picture of GOP. closed\_gop is flag data in which a thing with a picture refreshable independently of other GOP(s) in GOP is shown. broken\_link is flag data in which it is shown that B picture of the head in GOP cannot be correctly reproduced because of edit etc.

[0277] Only the data element defined by a user\_data() function is described as a history stream like an extension\_and\_user\_data(1) function and an extension\_and\_user\_data(0) function.

[0278] When group\_start\_code which shows the start code of a GOP layer does not exist in a history stream. The data element defined by these group\_of\_picture\_header() functions and an extension\_and\_user\_data(1) function is not described in the history stream. In that case it is the data element defined by the extension\_and\_user\_data(0) function. Next the data element defined by the picture\_header() function is described as a history stream.

[0279] The data element defined by the picture\_header() function. As shown in drawing 53 picture\_start\_code, temporal\_reference, picture\_coding\_type, vbv\_delay, full\_pel\_forward\_vector. They are forward\_f\_code, full\_pel\_backward\_vector, backward\_f\_code, extra\_bit\_picture and extra\_information\_picture.

[0280] Specifically, picture\_start\_code is data showing the start synchronization code of a picture layer. temporal\_reference is data reset at the head of GOP by the number which shows the display order of a picture. picture\_coding\_type is data in which a picture type is shown.

vbv\_delay is data in which the initial state of the virtual buffer at the time of random access is shown. full\_pel\_forward\_vector is data which the accuracy of a forward direction motion vector shows an integer unit or a half a pixel unit. forward\_f\_code is data showing a forward direction motion vector search range. full\_pel\_backward\_vector is data which the accuracy of an opposite direction motion vector shows an integer unit or a half a pixel unit.

backward\_f\_code is data showing an opposite direction motion vector search range. extra\_bit\_picture is a flag which shows existence of the additional information which follows.

When this extra\_bit\_picture is "1" extra\_information\_picture exists. Next when extra\_bit\_picture is "0" it is shown that there is no data following this.

extra\_information\_picture is the information reserved in the standard.

[0281] The data element defined as the next of the data element defined by the picture\_header() function by the picture\_coding\_extension() function as shown in drawing 54 is described as a history stream.

[0282] With the data element defined by this picture\_coding\_extension() function.

extension\_start\_code, extension\_start\_code\_identifier, f\_code[0][0], f\_code[0] and [1], f\_code[1][0], f\_code

[1][1], intra\_dc\_precision, picture\_structure, top\_field\_first, frame\_predictive\_frame\_dct, concealment

nt\_motion\_vectorsq\_scale\_typeintra\_vlc\_formatalternate\_scanrepeat\_firt\_fieldchroma\_420\_t  
ypelt comprises  
progressive\_framecomposite\_display\_flagv\_axisfield\_sequencesub\_carrierburst\_amplitudeand  
sub\_carrier\_phase.

[0283]extension\_start\_code is a start code which shows the start of the extension data of a picture layer. extension\_start\_code\_identifier is a code which shows which extended data is sent. f\_code [0] and [0] are data showing the level motion vector search range of the direction of a forward. f\_code [0] and [1] are data showing the vertical motion vector search range of the direction of a forward. f\_code [1] and [0] are data showing the level motion vector search range of the backward direction. f\_code [1] and [1] are data showing the vertical motion vector search range of the backward direction. intra\_dc\_precision is data showing the accuracy of a DC coefficient.

[0284]picture\_structure is data in which a frame structure or a field structure is shown. In the case of a field structurethey are the higher rank fieldthe low rank fieldor data set and shown. In the case of a frame structuretop\_field\_first is data which the first field shows a higher rank or a low rank. frame\_predictive\_frame\_dct is data in which it is shown in the case of a frame structure that prediction of frame mode DCT is only a frame mode.

concealment\_motion\_vectors is data in which it is shown that the motion vector for concealing a transmission error is attached to the Intra macro block. q\_scale\_type is data in which it is shown whether a linear quantization scale is used or a nonlinear quantization scale is used. intra\_vlc\_format is data in which it is shown whether another two-dimensional VLC is used for the Intra macro block.

[0285]alternate\_scan is data showing selection of whether a zigzag scan is used or to use an alternate scan. repeat\_firt\_field is data used 2:3 when pulldown. When the signal format of chroma\_420\_type is 4:2:0they are the same value as following progressive\_frameand data which expresses 0 when that is not right. progressive\_frame is data in which it is shown whether this picture can be scanned sequentially. composite\_display\_flag is data in which it is shown whether the source signal was a composite signal. v\_axis is data in which a source signal is used in the case of PAL. field\_sequence is data in which a source signal is used in the case of PAL. sub\_carrier is data in which a source signal is used in the case of PAL. burst\_amplitude is data in which a source signal is used in the case of PAL. sub\_carrier\_phase is data in which a source signal is used in the case of PAL.

[0286]The data element defined by extensions\_and\_user\_data (2) is described as a history stream by the next of the data element defined by the picture\_coding\_extension() function. This extension\_and\_user\_data (2) functionAs shown in drawing 50when an extension start code (extension\_start\_code) exists in a bit streamthe data element defined by an extension\_data() function is described. When an user-datum start code (user\_data\_start\_code) exists in a bit streamthe data element defined by a user\_data() function is described by the next of this data element. Howeverwhen an extension start code and an user-datum start code do not exist in a bit streamthe data element defined by the extension\_data() function and a user\_data() function is not described in BITTOTO ream.

[0287]The data element an extension\_data() function indicates extension\_start\_code to be as shown in drawing 55A quant\_matrix\_extension() functiona copyright\_extension() functionAnd it is a function for describing data EREMENETO defined by a picture\_display\_extension()

function as a history stream in a bit stream.

[0288]The data element defined by a `quant_matrix_extension()` functionAs shown in [drawing 56](#)  
`extension_start_code``extension_start_code_identifier``quant_matrix_extension_present_flag`  
`load_intra_quantizer_matrix``intra_quantizer_matrix`

[64]`load_non_intra_quantizer_matrix``non_intra_quantizer_matrix`

[64]`load_chroma_intra_quantizer_matrix`They are `chroma_intra_quantizer_matrix`

[64]`load_chroma_non_intra_quantizer_matrix`and `chroma_non_intra_quantizer_matrix` [64].

[0289]`extension_start_code` is a start code which shows the start of this quantizing-matrix extension. `extension_start_code_identifier` is a code which shows which extended data is sent. `quant_matrix_extension_present_flag` is data for whether the data element within this quantizing-matrix extension is effective or invalid to be shown. `load_intra_quantizer_matrix` is data in which existence of the quantization matrix data for Intra macro blocks is shown. `intra_quantizer_matrix` is data in which the value of the quantizing matrix for Intra macro blocks is shown.

[0290]`load_non_intra_quantizer_matrix` is data in which existence of the quantization matrix data for non-Intra macro blocks is shown. `non_intra_quantizer_matrix` is data showing the value of the quantizing matrix for non-Intra macro blocks. `load_chroma_intra_quantizer_matrix` is data in which existence of the quantizing-matrix data for color difference Intra macro blocks is shown. `chroma_intra_quantizer_matrix` is data in which the value of the quantizing matrix for color difference Intra macro blocks is shown. `load_chroma_non_intra_quantizer_matrix` is data in which existence of the quantizing-matrix data for color difference non-Intra macro blocks is shown. `chroma_non_intra_quantizer_matrix` is data in which the value of the quantizing matrix for color difference non-Intra macro blocks is shown.

[0291]The data element defined by a `copyright_extension()` functionLike and `extension_start_code` which are shown in [drawing](#)

[57](#)`extension_start_code``copyright_extension_present_flag`It comprises  
`copyright_flag``copyright_identifier``original_or_copy``copyright_number_1``copyright_number_2`and  
`copyright_number_3`.

[0292]`extension_start_code` is a start \*\*\*\* start code of a copyright extension.  
`extension_start_code_identifier` -- it is a code which shows which extension data is sent.  
`copyright_extension_present_flag` is data for whether the data element within this copyright extension is effective or invalid to be shown.

[0293]`copyright_flag` shows whether the right of a copy is granted to the coded video data to a following copyright extension or sequence end. `copyright_identifier` is data for identifying the registration agency of the right of a copy specified by ISO/IEC JTC/SC29. `original_or_copy` is data in which it is shown whether the data in a bit stream is original data or it is copy data.

`copyright_number_1` is data showing the bits 44-63 of a copyright number.

`copyright_number_2` is data showing the bits 22-43 of a copyright number.

`copyright_number_3` is data showing the bits 0-21 of a copyright number.

[0294]The data element defined by a `picture_display_extension()` functionAs shown in [drawing 58](#)they are

`extension_start_code``identifier``frame_center_horizontal_offset``frame_center_vertical_offset`  
`c`.

[0295]`extension_start_code_identifier` is a code which shows which extended data is sent.

frame\_center\_horizontal\_offset is data in which horizontal offset of display area is shown and can define a number of offset values defined by number\_of\_frame\_center\_offsets.

frame\_center\_vertical\_offset is data in which vertical offset is shown for display area -- a number of offset values defined by number\_of\_frame\_center\_offsets can be defined.

[0296] It returns to [drawing 47](#) again and the data element defined by a picture\_data() function is described by the next of the data element defined by an extension\_and\_user\_data (2) function as a history stream.

[0297] The data element defined by a picture\_data() function is a data element defined by a slice() function as shown in [drawing 59](#). However when slice\_start\_code which shows the start code of a slice() function does not exist in a bit stream the data element defined by this slice() function is not described in the bit stream.

[0298] As shown in [drawing 60a](#) slice() function

slice\_start\_code slice\_quantiser\_scale\_code intra\_slice\_flag Data elements such as intra\_slice\_reserved\_bits extra\_bit\_slice extra\_information\_slice and extra\_bit\_slice are functions for describing the data element defined by a macroblock() function as a history stream.

[0299] slice\_start\_code is a start code which shows the start of the data element defined by a slice() function. slice\_quantiser\_scale\_code is data in which the quantization step size set up to the macro block which exists in this slice layer is shown. However when quantiser\_scale\_code is set up for every macro block it is used by the data of macroblock\_quantiser\_scale\_code set up to each macro block giving priority.

[0300] intra\_slice\_flag is a flag which shows whether intra\_slice and reserved\_bits exist in a bit stream. intra\_slice is data in which it is shown whether a non Intra macro block exists in a slice layer. When either of the macro blocks in a slice layer is a non Intra macro block intra\_slice is set to "0" and intra\_slice is set to "1" when all the macro blocks in a slice layer are non Intra macro blocks. reserved\_bits is 7-bit data and takes the value of "0." extra\_bit\_slice is a flag which shows that additional information exists as a history stream and when extra\_information\_slice next exists it is set as "1." When additional information does not exist it is set as "0."

[0301] The data element defined by the macroblock() function is described as a history stream by the next of these data elements.

[0302] As shown in [drawing 61a](#) macroblock() function macroblock\_escape Data elements such as macroblock\_address\_increment and macroblock\_quantiser\_scale\_code They are a macroblock\_modes() function and a function for describing the data element defined by macroblock\_vectors (s) function.

[0303] macroblock\_escape is a fixed bit string which shows whether the horizontal difference of a reference macroblock and a front macro block is 34 or more. When the horizontal difference of a reference macroblock and a front macro block is 34 or more 33 is added to the value of macroblock\_address\_increment. macroblock\_address\_increment is data in which the horizontal difference of a reference macroblock and a front macro block is shown. If one macroblock\_escape exists before this macroblock\_address\_increment The value which added 33 to the value of this macroblock\_address\_increment serves as data in which the horizontal difference of a actual reference macroblock and a front macro block is shown.

[0304] macroblock\_quantiser\_scale\_code is the quantization step size set up for every macro block. Although slice\_quantiser\_scale\_code which shows the quantization step size of a slice layer is set to each slice layer When macroblock\_quantiser\_scale\_code is set up to the reference



macroblock this quantization step size is chosen.

[0305] The data element defined by a `macroblock_modes()` function is described by the next of `macroblock_address_increment`. A `macroblock_modes()` function as shown in [drawing 62](#) it is a function for describing data elements such as

`macroblock_type`, `frame_motion_type`, `field_motion_type` and `dct_type` as a history stream.

[0306] `macroblock_type` is data in which the coding type of a MAKUROGU block is shown. As shown in [drawing 65](#) thru/or [drawing 67](#) specifically `macroblock_type` is the variable length data generated from flags such as

`macroblock_quant_dct_type_flag`, `macroblock_motion_forward` and

`macroblock_motion_backward`. `macroblock_quant` as flag \*\* which shows whether `macroblock_quantiser_scale_code` for setting up quantization step size to a macro block is set up. When `macroblock_quantiser_scale_code` exists in a bit stream `macroblock_quant` takes the value of "1."

[0307] `dct_type_flag` is a flag (flag which shows whether in other words DCT is carried out) for whether `dct_type` which shows whether the reference macroblock is coded by frame DCT or field DCT exists to be shown. When `dct_type` exists in a bit stream this `dct_type_flag` takes the value of "1." `macroblock_motion_forward` is a flag which shows whether forward prediction of the reference macroblock is carried out and when forward prediction is carried out it takes the value of "1." `macroblock_motion_backward` is a flag which shows whether backward prediction of the reference macroblock is carried out and when backward prediction is carried out it takes the value of "1."

[0308] When `macroblock_motion_forward` or `macroblock_motion_backward` is "1" When picture structure is a frame and `frame_period_frame_dct` is "0" the data element which expresses `frame_motion_type` to the next of the data element showing `macroblock_type` is described. It is a flag which shows whether this `frame_period_frame_dct` and `frame_motion_type` exist in a bit stream.

[0309] `frame_motion_type` is a 2-bit code which shows the prediction type of the macro block of a frame. It is "00" if an estimated vector is a prediction type of a field base in two pieces. It is "11" if it is "10" if it is "01" if an estimated vector is a prediction type of a field base in one piece and an estimated vector is a prediction type of a frame base in one piece and an estimated vector is a prediction type of a DIARU prime in one piece.

[0310] When `macroblock_motion_forward` or `macroblock_motion_backward` is "1" When there is no picture structure in frame appearance the data element which expresses `field_motion_type` to the next of the data element showing `macroblock_type` is described.

[0311] `field_motion_type` is a 2-bit code which shows the motion prediction of the macro block of the field. It is "11" if it is "10" if it is "01" if an estimated vector is a prediction type of a field base in one piece and an estimated vector is a prediction type of an 18x8 macro-block base in two pieces and an estimated vector is a prediction type of a DIARU prime in one piece.

[0312] Picture structure shows with a frame that `frame_motion_type` exists in a bit stream in `frame_period_frame_dct` And the data element with which it expresses `dct_type` to the next of the data element showing `macroblock_type` when `frame_period_frame_dct` shows that `dct_type` exists in a bit stream is described. `dct_type` is data which DCT shows frame DCT mode and field DCT mode.

[0313] Return to [drawing 61](#) again and a reference macroblock is a forward prediction macro

block or a reference macroblock is the intra macroblock and in one case of the macro blocks of concealed processing. The data element defined by a motion\_vectors (0) function is described. When a reference macroblock is a backward prediction macroblock the data element defined by a motion\_vectors (1) function is described. A motion\_vectors (0) function is a function for describing the data element about the motion vector of No. 1 and a motion\_vectors (1) function is a function for describing the data element about the motion vector of No. 2.

[0314] A motion\_vectors (s) function is a function for describing the data element about a motion vector as shown in [drawing 63](#).

[0315] When the motion vector is not using DIARU prime prediction mode by one piece, the data element defined by motion\_vertical\_field\_select [0][s] and motion\_vector (0s) is described.

[0316] This motion\_vertical\_field\_select [r] and [s] The 1st motion vector (it may be which vector of the front or back) is a flag which shows whether it is the vector made with reference to the bottom field or it is the vector made with reference to the top field. This index "r" is an index which shows whether it is which vector of the vector of No. 1 or the vector of No. 2 and is an index with which as for "s" the prediction direction shows any of the front or backward prediction they are.

[0317] A motion\_vector (rs) function As shown in [drawing 64](#) it is a function for describing the data row about motion\_code [r][s] and [t] the data row about motion\_residual [r][s] and [t] and the data showing dmvector [t].

[0318] motion\_code [r][s] and [t] are variable-length data which expresses the size of a motion vector in -16 ~ +16. motion\_residual [r][s] and [t] are variable-length data showing the remainder of a motion vector. Therefore the value of this motion\_code [r][s][t] and motion\_residual [r][s] and [t] can describe a detailed motion vector. In order that dmvector [t] may generate the motion vector in one field (for example let a top field be one field to a bottom field) at the time of DIARU prime prediction mode The scale of the existing motion vector is carried out according to the time distance and in order to make a gap of the perpendicular direction between the lines of a top field and a bottom field reflect it is data which amends to a perpendicular direction. This index "r" is an index which shows whether it is which vector of the vector of No. 1 or the vector of No. 2 and is an index with which as for "s" the prediction direction shows any of the front or backward prediction they are. "s" is data in which it is shown whether a motion vector is a vertical ingredient or it is a horizontal ingredient.

[0319] The data row which is shown in [drawing 64](#) and expresses horizontal motion\_coder [r][s] and [0] first by a motion\_vector (rs) function is described as a history stream. The number of bits of the both sides of motion\_residual [0][s][t] and motion\_residual [1][s] and [t] Since it is shown by f\_code [s] and [t] when f\_code [s] and [t] are not 1 it will be shown that motion\_residual [r][s] and [t] exist in a bit stream. That motion\_residual [r] of a horizontal component [s] and [0] are not "1" and motion\_code [r] of a horizontal component [s] and [0] are not "0" Since it means that the data element showing motion\_residual [r][s] and [0] exists and the horizontal component of a motion vector exists in a bit stream that case the data element showing motion\_residual [r] of a horizontal component [s] and [0] is described.

[0320] Then the data row showing vertical motion\_coder [r][s] and [1] is described as a history stream. Similarly the number of bits of the both sides of motion\_residual [0][s][t] and motion\_residual [1][s] and [t] Since it is shown by f\_code [s] and [t] when f\_code [s] and [t] are not 1 it will be meant that motion\_residual [r][s] and [t] exist in a bit stream. That

motion\_residual [r][s] and [1] are not "1" and motion\_code [r][s] and [1] are not "0" Since it means that the data element showing motion\_residual [r][s] and [1] exists and the perpendicular direction ingredient of a motion vector exists in a bit stream In that case the data element showing motion\_residual [r] of a perpendicular direction ingredient [s] and [1] is described.

[0321] In a variable length format in order to decrease the bit rate to transmit hysteresis information is reducible.

[0322] Namely although macroblock\_type and motion\_vectors() transmits When not transmitting quantiser\_scale\_code the bit rate can be decreased by setting slice\_quantiser\_scale\_code to "00000."

[0323] Only macroblock\_type transmits it and motion\_vectors() When not transmitting quantiser\_scale\_code and dct\_type the bit rate can be decreased by using "not coded" as macroblock\_type.

[0324] When transmitting only picture\_coding\_type and transmitting not all the information below slice() further again the bit rate can be decreased by using picture\_data() without slice\_start\_code.

[0325] When keeping continuous "0" in user\_data from above coming 1 was inserted every 22 bits but it may not be every 22 bits. [ 23-bit ] It is also possible to count the number of continuous "0" and not to insert "1" but to investigate Byte\_align and to make it insert.

[0326] In MPEG although 23-bit generating of continuous "0" is forbidden when only the case where 23 bits continues from a byte's head is actually made into a problem and 0 [ 23-bit ] continues not from a byte's head but from the middle it is not considered as a problem.

Therefore it may be made to insert "1" in positions other than LSB every 24 bits for example.

[0327] Although hysteresis information was carried out above at the form near video elementary stream it may be made the form near packetized elementary stream or transport stream. It can also be made other places although the place of user\_data of Elementary Stream was carried out the picture\_data front.

[0328] A user can be provided with the computer program which performs each above-mentioned processing via network distribution media such as the Internet and a digital satellite besides the distribution medium which consists of information recording media such as a magnetic disk and CD-ROM.

[0329]

[Effect of the Invention] Since the coding hysteresis information inserted in the user data area of the picture layer of a bit stream was decoded like the above according to the decoding device according to claim 1 the decoding method according to claim 2 and the distribution medium according to claim 3 it becomes possible to control degradation of the picture accompanying recoding with the device of a small scale.

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## DESCRIPTION OF DRAWINGS

[Brief Description of the Drawings]

[Drawing 1] It is a figure explaining the principle of efficient coding.

[Drawing 2] It is a figure explaining the picture type in the case of compressing image data.

[Drawing 3] It is a figure explaining the picture type in the case of compressing image data.

[Drawing 4] It is a figure explaining the principle which codes a dynamic image signal.

[Drawing 5] It is a block diagram coding a dynamic image signal and in which showing the composition of the device to decode.

[Drawing 6] It is a figure explaining format conversion.

[Drawing 7] It is a block diagram showing the composition of the encoder 18 of drawing 5.

[Drawing 8] It is a figure explaining operation of the prediction mode switch circuit 52 of drawing 7.

[Drawing 9] It is a figure explaining operation of the prediction mode switch circuit 52 of drawing 7.

[Drawing 10] It is a figure explaining operation of the prediction mode switch circuit 52 of drawing 7.

[Drawing 11] It is a figure explaining operation of the prediction mode switch circuit 52 of drawing 7.

[Drawing 12] It is a block diagram showing the composition of the decoder 31 of drawing 5.

[Drawing 13] It is a figure explaining the SNR control corresponding to a picture type.

[Drawing 14] It is a block diagram showing the composition of the transformer coder 101 which applied this invention.

[Drawing 15] It is a block diagram showing the more detailed composition of the transformer coder 101 of drawing 14.

[Drawing 16] It is a block diagram showing the composition of the decoder 111 built in the decoding device 102 of drawing 14.

[Drawing 17] It is a figure explaining the pixel of a macro block.

[Drawing 18] It is a figure explaining the field where an encoding parameter is recorded.

[Drawing 19] It is a block diagram showing the composition of the encoder 121 built in the coding equipment 106 of drawing 14.

[Drawing 20] It is a block diagram showing the example of composition of history FOMATTA 211 of drawing 15.

[Drawing 21] It is a block diagram showing the example of composition of the history decoder 203 of drawing 15.

[Drawing 22] It is a block diagram showing the example of composition of the converter 212 of drawing 15.

[Drawing 23] It is a block diagram showing the example of composition of the staff circuit 323 of drawing 22.

[Drawing 24] It is a timing chart explaining operation of the converter 212 of drawing 22.

[Drawing 25] It is a block diagram showing the example of composition of the converter 202 of drawing 15.

[Drawing 26] It is a block diagram showing the example of composition of the DIRITO circuit 343 of drawing 25.

[Drawing 27] It is a block diagram showing other examples of composition of the converter 212 of drawing 15.

[Drawing 28] It is a block diagram showing other examples of composition of the converter 202 of drawing 15.

[Drawing 29] It is a block diagram showing the example of composition of the user-datum formatter 213 of drawing 15.

[Drawing 30] The transformer coder 101 of drawing 14 is a figure showing the state where it is actually used.

[Drawing 31] It is a figure explaining the field where an encoding parameter is recorded.

[Drawing 32] It is a flow chart explaining the picture type decision processing of the coding equipment 106 of drawing 14 which can be changed.

[Drawing 33] It is a figure showing the example in which a picture type is changed.

[Drawing 34] It is a figure showing other examples in which a picture type is changed.

[Drawing 35] It is a figure explaining quantized control processing of the coding equipment 106 of drawing 14.

[Drawing 36] It is a flow chart explaining quantized control processing of the coding equipment 106 of drawing 14.

[Drawing 37] It is a block diagram showing the composition of the transformer coder 101 by which close coupling was carried out.

[Drawing 38] It is a figure explaining the syntax of an MPEG stream.

[Drawing 39] It is a figure explaining the composition of the syntax of drawing 38.

[Drawing 40] It is a figure explaining the syntax of `history_stream()` which records fixed-length hysteresis information.

[Drawing 41] It is a figure explaining the syntax of `history_stream()` which records fixed-length hysteresis information.

[Drawing 42] It is a figure explaining the syntax of `history_stream()` which records fixed-length hysteresis information.

[Drawing 43] It is a figure explaining the syntax of `history_stream()` which records fixed-length hysteresis information.

[Drawing 44] It is a figure explaining the syntax of `history_stream()` which records fixed-length hysteresis information.

[Drawing 45] It is a figure explaining the syntax of `history_stream()` which records fixed-length hysteresis information.

[Drawing 46] It is a figure explaining the syntax of `history_stream()` which records fixed-length hysteresis information.

[Drawing 47] It is a figure explaining the syntax of `history_stream()` which records variable-length hysteresis information.

[Drawing 48] It is a figure explaining the syntax of `sequence_header()`.

[Drawing 49] It is a figure explaining the syntax of `sequence_extension()`.

[Drawing 50] It is a figure explaining the syntax of `extension_and_user_data()`.

[Drawing 51] It is a figure explaining the syntax of `user_data()`.

[Drawing 52] It is a figure explaining the syntax of `group_of_pictures_header()`.

[Drawing 53] It is a figure explaining the syntax of `picture_header()`.

[Drawing 54] It is a figure explaining the syntax of `picture_coding_extension()`.

[Drawing 55] It is a figure explaining the syntax of `extension_data()`.

[Drawing 56] It is a figure explaining the syntax of `quant_matrix_extension()`.

[Drawing 57] It is a figure explaining the syntax of `copyright_extension()`.

[Drawing 58] It is a figure explaining the syntax of `picture_display_extension()`.

[Drawing 59] It is a figure explaining the syntax of `picture_data()`.

[Drawing 60] It is a figure explaining the syntax of `slice()`.

[Drawing 61] It is a figure explaining the syntax of macroblock().

[Drawing 62] It is a figure explaining the syntax of macroblock\_modes().

[Drawing 63] It is a figure explaining the syntax of motion\_vectors (s).

[Drawing 64] It is a figure explaining the syntax of motion\_vector (rs).

[Drawing 65] It is a figure explaining the variable length code of macroblock\_type to I picture.

[Drawing 66] It is a figure explaining the variable length code of macroblock\_type to P picture.

[Drawing 67] It is a figure explaining the variable length code of macroblock\_type to B picture.

[Drawing 68] It is a block diagram showing an example of the composition of the conventional transformer coder 131.

[Drawing 69] It is a block diagram showing an example of the composition of the conventional transformer coder 131.

[Drawing 70] It is a figure explaining conventional coding equipment and arrangement of a decoding device.

[Description of Notations]

1 Coding equipment and 2 A decoding device and 3. A recording medium 12 and 13 A/D converters 14 A frame memory and 15 A luminance-signal frame memory 16 A color-difference-signal frame memory 17 format conversion circuits and 18 [ A luminance-signal frame memory and 35 / A color-difference-signal frame memory and 36 and 37. ] An encoder and 31 A decoder 32 format conversion circuits and 33 A frame memory and 34 A D/A converter and 50 motion vector detection circuits 51 A frame memory and 52 A prediction mode switching circuit 53 Operation part and 54 A prediction decision circuit and 55. A DCT mode switching circuit and 56 DCT circuits 57 A quantization circuit and 58 variable-length-coding circuits 59 A transmission buffer and 60 An inverse quantizing circuit 61 IDCT circuit and 62 A computing unit and 63. A frame memory 64 motion compensation circuits and 81. A receive buffer and 82 A variable length decoding circuit 83 An inverse quantizing circuit 84 IDCT circuit and 85 [ \*\*\*\*\*. ] A computing unit 86 frame memories 87 motion compensation circuits and 101 A transformer coder and 102 A decoding device 103 encoding-parameter multiplexer 105 encoding-parameter decollator and 106 \*\*106 SDTI and 111 [ A transformer coder and 132 / A decoding device and 133 / Coding equipment 134 motion detection parts and 135 / Coding part ] A decoder and 112 A variable length decoding circuit and 121 An encoder 122 encoding-parameter controller and 131